

Control Bytes are Constructed in Hex like this:

0xXY

Where X is the direction and Y is the speed, here are some tables:

0x0Y	Stop		0xX0	Stop
0x1Y	Straight / Forward		0xX1	Slowest
0x2Y	Straight / Backward		0xX2	Way Way Slow
0x3Y	Left / No Drive		0xX3	Way Slow
0x4Y	Right / No Drive		0xX4	Less Way Slow
0x5Y	Left / Forward		0xX5	Slow
0x6Y	Right / Forward		0xX6	Easy-Going
0x7Y	Left / Backward		0xX7	Cruising
0x8Y	Right / Backward		0xX8	Moving Right Along
			0xX9	Moving Quick
			0xXA	Moving Quicker
			0xXB	Moving Pretty Darn Quick
			0xXC	Fast
			0xXD	Faster
			0xXE	Fastest
			0xFF	I lied, this is fastest.

For example: If you want to drive left pretty darn quick, just send a 0x5B. If you want to backup to the right slowly, send a 0x85. All commands are sent as single bytes at 9600 baud, 8-N-1.

Of course, if you're not a fan of this command set, there is a 6-pin ISP header on the board and the firmware source code is available on the product page. Feel free to put together your own set of commands!