



TPS65263, 4.5- to 18-V Input Voltage, 3-A/2-A/2-A Output Current Triple Synchronous Step-Down Converter With I²C Controlled Dynamic Voltage Scaling

1 Features

- Operating Input Voltage Range 4.5- to 18-V
Continuous Output Current 3 A/2 A/2 A
- I²C Controlled 7-Bits VID Programmable Output Voltage from 0.68 to 1.95 V With 10-mV Voltage Step for Each Buck
- I²C Controlled VID Voltage Transition Slew Rate
- I²C Read Back Power Good Status, Overcurrent Warning for Each Buck
- I²C Read Back Die Temperature Warning
- I²C Compatible Interface With Standard Mode (100 kHz) and Fast Mode (400 kHz)
- Feedback Reference Voltage 0.6 V $\pm$ 1%
- Fixed 600-kHz Frequency
- Dedicated Enable and Soft Start Pins for Each Buck
- Thermal Overloading Protection

2 Applications

- DTV LCD Panel
- Set-Top Boxes
- Home Gateway and Access Point Networks
- Surveillance

3 Description

The TPS65263 incorporates triple synchronous buck converters with 4.5- to 18-V wide input voltage range that encompassed most intermediate bus voltage operating off 5-, 9-, 12-, or 15-V power bus or battery. The converter, with constant frequency peak current mode, is designed to simplify its application while giving designers options to optimize the system according to targeted applications. The device operates in 600 kHz with 180° out-of-phase between buck1 and buck2, buck3 (buck2 and buck3 run in phase).

The initial startup voltage of each buck can be set with external feedback resistors. The output voltage of each buck can be dynamically scaled from 0.68 to 1.95 V in 10-mV step with I²C controlled 7 bits VID. The VID voltage transition slew rate is programmable with 3-bits control through I²C bus to optimize overshoot/undershoot during VID voltage transition.

Each buck in TPS65263 can be I²C controlled for enabling/disabling output voltage, setting the pulse skipping mode (PSM) or force continuous current mode (FCC) at light load condition and reading the power good status, overcurrent warning and die temperature warning.

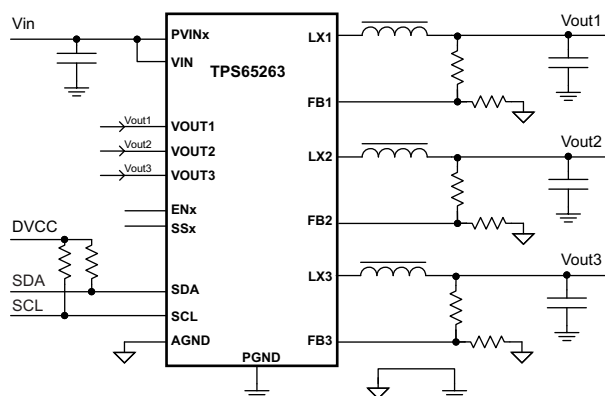
The TPS65263 features overvoltage, overcurrent, short-circuit, and overtemperature protection.

Device Information⁽¹⁾

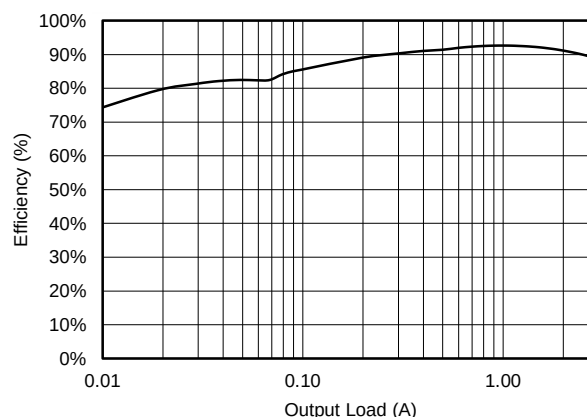
PART NUMBER	PACKAGE	BODY SIZE (NOM)
TPS65263	VQFN (32)	5.00 mm $\times$ 5.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

4 Typical Application



Efficiency vs Output Load



A. $V_{IN} = 12\text{ V}$; $V_{OUT} = 3.3\text{ V}$



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5 Revision History

Changes from Original (June 2014) to Revision A

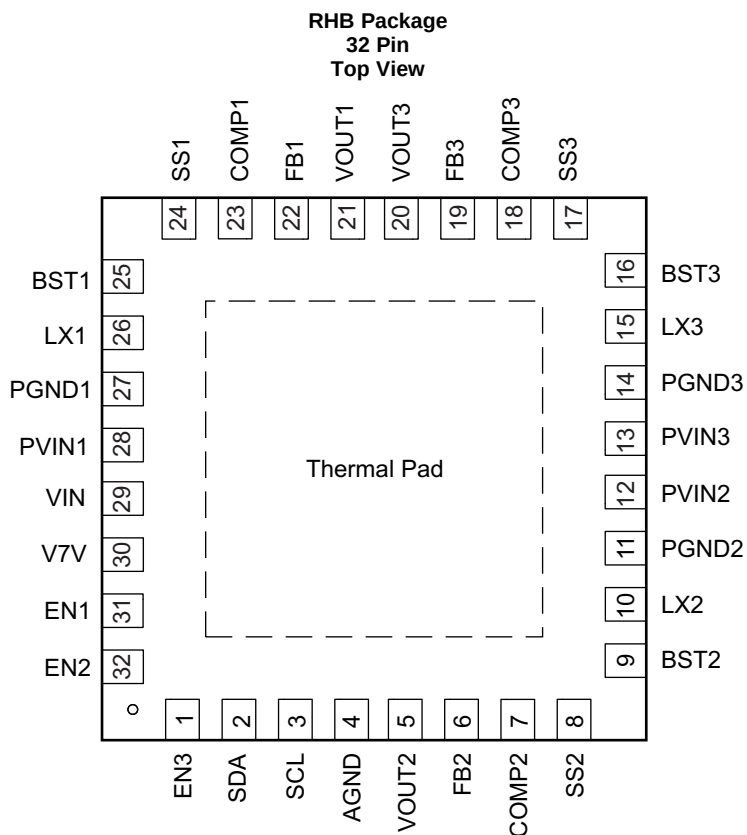
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• Updated device from product preview to production data	1
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6 Device Comparison Table

PART NUMBER	DESCRIPTION	COMMENTS
TPS65261/-1	4.5 to 18 V, triple bucks with input voltage power failure indicator	Triple bucks 3-A/2-A/2-A output current, features an open drain RESET signal to monitor input power failure, automatic power sequencing
TPS65262/-1	4.5 to 18 V, triple bucks with dual adjustable LDOs	Triple bucks 3-A/1-A/1-A output current, automatic power sequencing. dual LDOs: TPS65262, 200 mA/100 mA; TPS65262-1, 350 mA/150 mA
TPS65287	4.5 to 18 V, triple bucks with power switch and push button control	Triple bucks 3-A/2-A/2-A output current, up to 2.1-A USB power with over current setting by external resistor, push button control for intelligent system power-on/power-off operation
TPS65288	4.5 to 18 V, triple bucks with dual power switches	Triple bucks 3-A/2-A/2-A output current, 2 USB power switches current limiting at typical 1.2 A (0.8, 1.0, 1.4, 1.6, 1.8, 2.0, 2.2 A available with manufacture trim options)

7 Pin Configuration and Functions



(There is no electric signal down bonded to thermal pad inside IC.
Exposed thermal pad must be soldered to PCB for optimal thermal performance.)

Pin Functions

PIN		DESCRIPTION
NAME	NO.	
EN3	1	Enable for buck3. Float to enable. Can use this pin to adjust the input undervoltage lockout (UVLO) of buck3 with a resistor divider.
SDA	2	I ² C interface data pin
SCL	3	I ² C interface clock pin
AGND	4	Analog ground common to buck controllers and other analog circuits. It must be routed separately from high current power grounds to the (–) terminal of bypass capacitor of input voltage VIN.

Pin Functions (continued)

PIN		DESCRIPTION
NAME	NO.	
VOUT2	5	Buck2 output voltage sense pin.
FB2	6	Feedback Kelvin sensing pin for buck2 output voltage. Connect this pin to buck2 resistor divider.
COMP2	7	Error amplifier output and Loop compensation pin for buck2. Connect a series resistor and capacitor to compensate the control loop of buck2 with peak current PWM mode.
SS2	8	Soft-start and tracking input for buck2. An internal 5 μ A pullup current source is connected to this pin. The soft-start time can be programmed by connecting a capacitor between this pin and ground.
BST2	9	Boot strapped supply to the high side floating gate driver in buck2. Connect a capacitor (recommend 47nF) from BST2 pin to LX2 pin.
LX2	10	Switching node connection to the inductor and bootstrap capacitor for buck2. The voltage swing at this pin is from a diode voltage below the ground up to PVIN2 voltage.
PGND2	11	Power ground connection of buck2. Connect PGND2 pin as close as practical to the (–) terminal of PVIN2 input ceramic capacitor.
PVIN2	12	Input power supply for buck2. Connect PVIN2 pin as close as practical to the (+) terminal of an input ceramic capacitor (suggest 10 μ F).
PVIN3	13	Input power supply for buck3. Connect PVIN3 pin as close as practical to the (+) terminal of an input ceramic capacitor (suggest 10 μ F).
PGND3	14	Power ground connection of buck3. Connect PGND3 pin as close as practical to the (–) terminal of PVIN3 input ceramic capacitor.
LX3	15	Switching node connection to the inductor and bootstrap capacitor for buck3. The voltage swing at this pin is from a diode voltage below the ground up to PVIN3 voltage.
BST3	16	Boot strapped supply to the high side floating gate driver in buck3. Connect a capacitor (recommend 47 nF) from BST3 pin to LX3 pin.
SS3	17	Soft-start and tracking input for buck3. An internal 5- μ A pullup current source is connected to this pin. The soft-start time can be programmed by connecting a capacitor between this pin and ground.
COMP3	18	Error amplifier output and Loop compensation pin for buck3. Connect a series resistor and capacitor to compensate the control loop of buck3 with peak current PWM mode.
FB3	19	Feedback Kelvin sensing pin for buck3 output voltage. Connect this pin to buck3 resistor divider.
VOUT3	20	Buck3 output voltage sense pin.
VOUT1	21	Buck1 output voltage sense pin.
FB1	22	Feedback Kelvin sensing pin for buck1 output voltage. Connect this pin to buck1 resistor divider.
COMP1	23	Error amplifier output and Loop compensation pin for buck1. Connect a series resistor and capacitor to compensate the control loop of buck1 with peak current PWM mode.
SS1	24	Soft-start and tracking input for buck1. An internal 5- μ A pullup current source is connected to this pin. The soft-start time can be programmed by connecting a capacitor between this pin and ground.
BST1	25	Boot strapped supply to the high side floating gate driver in buck1. Connect a capacitor (recommend 47 nF) from BST1 pin to LX1 pin.
LX1	26	Switching node connection to the inductor and bootstrap capacitor for buck1. The voltage swing at this pin is from a diode voltage below the ground up to PVIN1 voltage.
PGND1	27	Power ground connection of Buck1. Connect PGND1 pin as close as practical to the (–) terminal of PVIN1 input ceramic capacitor.
PVIN1	28	Input power supply for buck1. Connect PVIN1 pin as close as practical to the (+) terminal of an input ceramic capacitor (suggest 10 μ F).
VIN	29	Buck controller power supply.
V7V	30	Internal LDO for gate driver and internal controller. Connect a 1- μ F capacitor from the pin to power ground.
EN1	31	Enable for buck1. Float to enable. Can use this pin to adjust the input UVLO of buck1 with a resistor divider.
EN2	32	Enable for buck2. Float to enable. Can use this pin to adjust the input UVLO of buck2 with a resistor divider.
PAD	—	There is no electric signal down bonded to thermal pad inside IC. Exposed thermal pad must be soldered to PCB for optimal thermal performance.

8 Specifications

8.1 Absolute Maximum Ratings

over operating free-air temperature (unless otherwise noted) ⁽¹⁾

		MIN	MAX	UNIT
Voltage	PVIN1, PVIN2, PVIN3, VIN	−0.3	20	V
	LX1, LX2, LX3 (maximum withstand voltage transient <20 ns)	−1.0	20	
	BST1, BST2, BST3 referenced to LX1, LX2, LX3 pins respectively	−0.3	7	
	EN1, EN2, EN3, V7V, VOUT1, VOUT2, VOUT3, SCL, SDA	−0.3	7	
	FB1, FB2, FB3, COMP1, COMP2, COMP3, SS1, SS2, SS3	−0.3	3.6	
	AGND, PGND1, PGND2, PGND3	−0.3	0.3	
T _J	Operating junction temperature	−40	125	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

8.2 Handling Ratings

			MIN	MAX	UNIT
T _{stg}	Storage temperature range		−55	150	°C
V _(ESD)	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽¹⁾	−2000	2000	V
		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins ⁽²⁾	−500	500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

8.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
Voltage	PVIN1, PVIN2, PVIN3, VIN	4.5	18	V
	LX1, LX2, LX3 (Maximum withstand voltage transient <20 ns)	−0.8	18	
	BST1, BST2, BST3 referenced to LX1, LX2, LX3 pins respectively	−0.1	6.8	
	EN1, EN2, EN3, V7V, VOUT1, VOUT2, VOUT3, SCL, SDA	−0.1	6.3	
	FB1, FB2, FB3, COMP1, COMP2, COMP3, SS1, SS2, SS3	−0.1	3	
T _A	Operating ambient temperature	−40	85	°C
T _J	Operating junction temperature	−40	125	°C

8.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TPS65263	UNIT
		RHB (32 PINS)	
R _{θJA}	Junction-to-ambient thermal resistance	33.3	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	25.7	
R _{θJB}	Junction-to-board thermal resistance	7.4	
Ψ _{JT}	Junction-to-top characterization parameter	0.3	
Ψ _{JB}	Junction-to-board characterization parameter	7.3	
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	2.1	

- (1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).

8.5 Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
INPUT SUPPLY VOLTAGE						
VIN	Input voltage range		4.5		18	V
UVLO	VIN undervoltage lockout	VIN rising	4	4.25	4.5	V
		VIN falling	3.5	3.75	4	V
		Hysteresis		500		mV
IDDSDN	Shutdown supply current	EN1 = EN2 = EN3 = 0 V		8		μA
IDDQ_NSW	Input quiescent current without buck1/2/3 switching	EN1 = EN2 = EN3 = 5 V, FB1 = FB2 = FB3 = 0.8 V		740		μA
IDDQ_NSW1		EN1 = 5 V, EN2 = EN3 = 0 V, FB1 = 0.8 V		360		μA
IDDQ_NSW2		EN2 = 5 V, EN1 = EN3 = 0 V, FB2 = 0.8 V		380		μA
IDDQ_NSW3		EN3 = 5 V, EN1 = EN2 = 0 V, FB3 = 0.8 V		380		μA
V7V	V7V LDO output voltage	V7V load current = 0 A	6	6.3	6.6	V
I _{OC} P_V7V	V7V LDO current limit			185		mA
FEEDBACK VOLTAGE REFERENCE						
VFB	Feedback voltage	V _{COMP} = 1.2 V, T _J = 25°C	0.595	0.6	0.605	V
		V _{COMP} = 1.2 V, T _J = –40°C to 125°C	0.594	0.6	0.606	V
V _{LIN} REG_BUCK	Line regulation-DC ⁽¹⁾	I _{OUT1} = 1.5 A, I _{OUT2} = 1 A, I _{OUT3} = 1 A, 5 V < P _{VIN} x < 18 V		0.002		%/V
V _{LOAD} REG_BUCK	Load regulation-DC ⁽¹⁾	I _{OUTx} = (10-100%) × I _{OUTx_max}		0.02		%/A
BUCK1, BUCK2, BUCK3						
V _{ENXH}	EN1/2/3 high level input voltage			1.2	1.26	V
V _{ENXL}	EN1/2/3 low level input voltage		1.1	1.15		V
I _{ENX1}	EN1/2/3 pullup current	ENx = 1 V		3.8		μA
I _{ENX2}	EN1/2/3 pullup current	ENx = 1.5 V		6.8		μA
I _{ENhys}	Hysteresis current			3		μA
I _{SSX}	Soft start charging current		4.3	5	6	μA
T _{ON_MIN}	Minimum on time			80	100	ns
G _{m_EA}	Error amplifier trans-conductance	–2 μA < I _{COMPX} < 2 μA		300		μS
G _{m_PS1/2/3}	COMP1/2/3 voltage to inductor current Gm ⁽¹⁾	I _{LX} = 0.5 A		7.4		A/V
I _{LIMIT1}	Buck1 peak inductor current limit		4.5	5.5	6.5	A
I _{LIMITSOURCE1}	Buck1 low side source current limit			4.4		A
I _{LIMITSINK1}	Buck1 low side sink current limit			1.3		
I _{LIMIT2/3}	buck2/3 peak inductor current limit		2.6	3.3	4	A
I _{LIMITSOURCE2/3}	Buck2/3 low side source current limit			2.5		
I _{LIMITSINK2/3}	Buck2/3 low side sink current limit			1		A
R _{dson_HS1}	Buck1 high-side switch resistance	VIN = 12 V		105		mΩ
R _{dson_LS1}	Buck1 low-side switch resistance	VIN = 12 V		65		mΩ
R _{dson_HS2}	Buck2 high-side switch resistance	VIN = 12 V		140		mΩ
R _{dson_LS2}	Buck2 low-side switch resistance	VIN = 12 V		90		mΩ
R _{dson_HS3}	Buck3 high-side switch resistance	VIN = 12 V		140		mΩ
R _{dson_LS3}	Buck3 low-side switch resistance	VIN = 12 V		90		mΩ
HICCUP TIMING						
T _{Hiccup_wait}	Over current wait time ⁽¹⁾			0.5		ms
T _{Hiccup_re}	Hiccup time before restart ⁽¹⁾			14		ms
OSCILLATOR						
F _{SW}	Switching frequency		550	600	650	kHz

(1) Lab validation result.

Electrical Characteristics (continued)

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
THERMAL PROTECTION						
T _{TRIP_OTP}	Thermal protection trip point ⁽²⁾	Temperature rising		160		°C
T _{HYST_OTP}	Thermal protection Hysteresis ⁽²⁾	Hysteresis		20		°C
I²C INTERFACE						
Addr	Address ⁽³⁾	0x60H				
V _{IH} SDA,SCL	Input high voltage				2	V
V _{IL} SDA,SCL	Input low voltage		0.4			V
I _I	Input current	SDA, SCL, V _I = 0.4 to 4.5 V	–10		10	μA
V _{OL} SDA	SDA output low voltage	SDA open drain, I _{OL} = 4 mA			0.4	V
f _(SCL)	Maximum SCL clock frequency ⁽³⁾		400			kHz
t _{BUF}	Bus free time between a STOP and START condition ⁽³⁾		1.3			μs
t _{HD_STA}	Hold time (repeated) START condition ⁽³⁾		0.6			μs
t _{SU_STO}	Setup time for STOP condition ⁽³⁾		0.6			μs
t _{LOW}	LOW Period of the SCL Clock ⁽³⁾		1.3			μs
t _{HIGH}	HIGH period of the SCL clock ⁽³⁾		0.6			μs
t _{SU_STA}	Setup time for a repeated START condition ⁽³⁾		0.6			μs
t _{SU_DAT}	Data setup time ⁽³⁾		0.1			μs
t _{HD_DAT}	Data hold time ⁽³⁾		0		0.9	μs
t _{RCL}	Rise time of SCL signal ⁽³⁾	Capacitance of one bus line (pF)	20 + 0.1CB		300	ns
t _{RCL1}	Rise time of SCL signal after a repeated START condition and after an acknowledge BIT ⁽³⁾	Capacitance of one bus line (pF)	20 + 0.1CB		300	ns
t _{FCL}	Fall time of SCL signal ⁽³⁾	Capacitance of one bus line (pF)	20 + 0.1CB		300	ns
t _{RDA}	Rise time of SDA signal ⁽³⁾	Capacitance of one bus line (pF)	20 + 0.1CB		300	ns
t _{FDA}	Fall time of SDA signal ⁽³⁾	Capacitance of one bus line (pF)	20 + 0.1CB		300	ns
C _B	Capacitance of bus line(SCL and SDA) ⁽³⁾				400	pF

(2) Lab validation result.

(3) Not production tested.

8.6 Typical Characteristics

$T_A = 25^\circ\text{C}$, $V_{IN} = 12\text{ V}$, $V_{OUT1} = 1.5\text{ V}$, $V_{OUT2} = 1.2\text{ V}$, $V_{OUT3} = 2.5\text{ V}$, $F_{SW} = 600\text{ kHz}$ (unless otherwise noted)

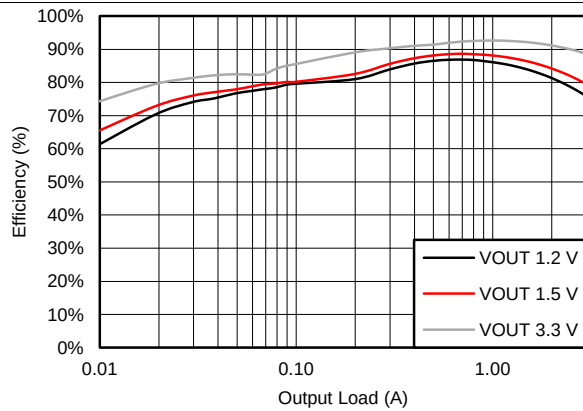


Figure 1. BUCK1 Efficiency

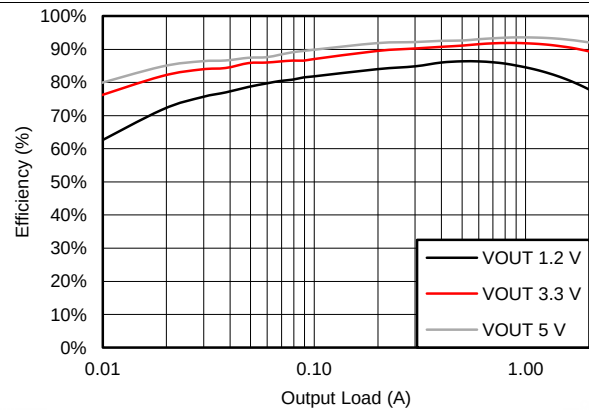


Figure 2. BUCK2 Efficiency

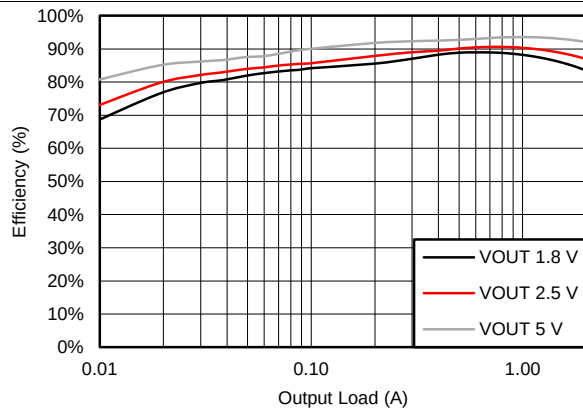


Figure 3. BUCK3 Efficiency

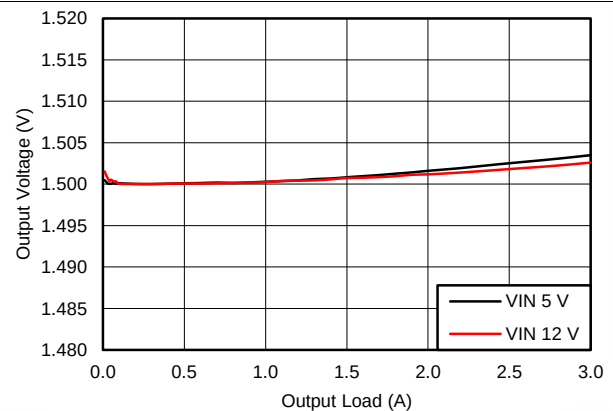


Figure 4. BUCK1 Load Regulation

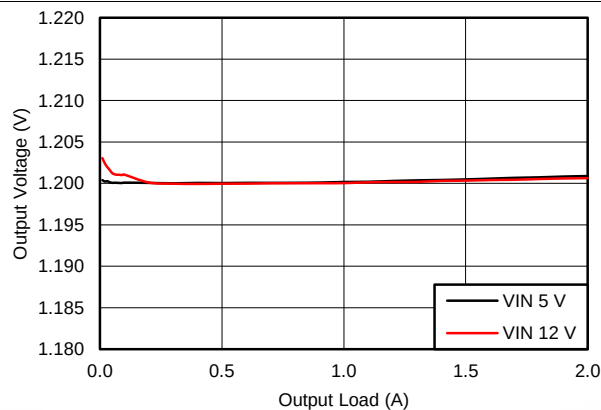


Figure 5. BUCK2 Load Regulation

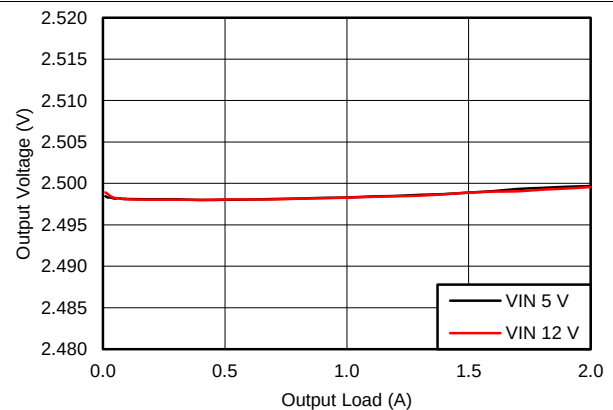


Figure 6. BUCK3 Load Regulation

Typical Characteristics (continued)

$T_A = 25^\circ\text{C}$, $V_{IN} = 12\text{ V}$, $V_{OUT1} = 1.5\text{ V}$, $V_{OUT2} = 1.2\text{ V}$, $V_{OUT3} = 2.5\text{ V}$, $F_{SW} = 600\text{ kHz}$ (unless otherwise noted)

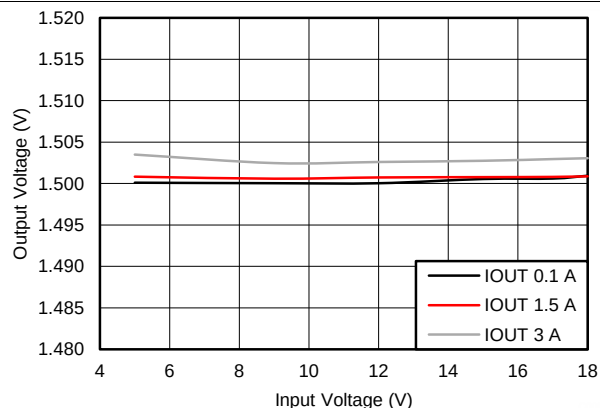


Figure 7. BUCK1, Line Regulation

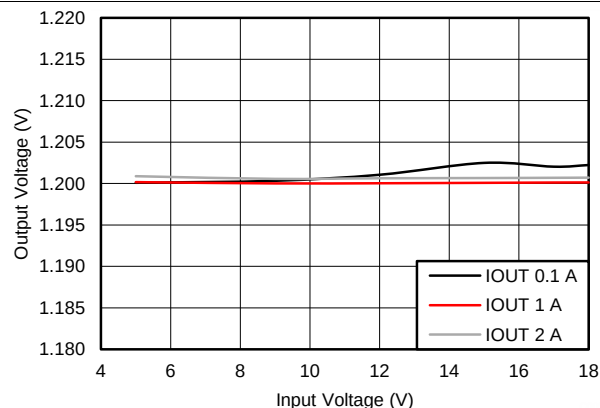


Figure 8. BUCK2, Line Regulation

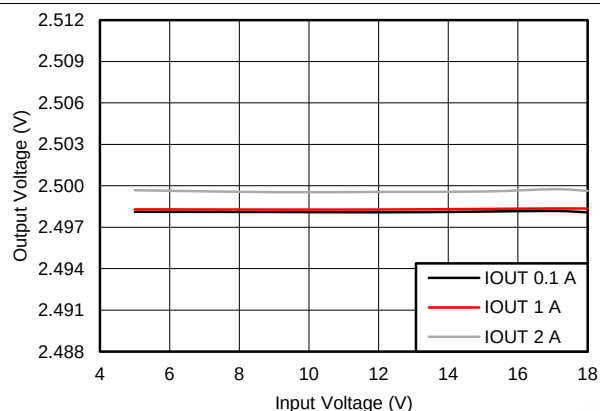


Figure 9. BUCK3, Line Regulation

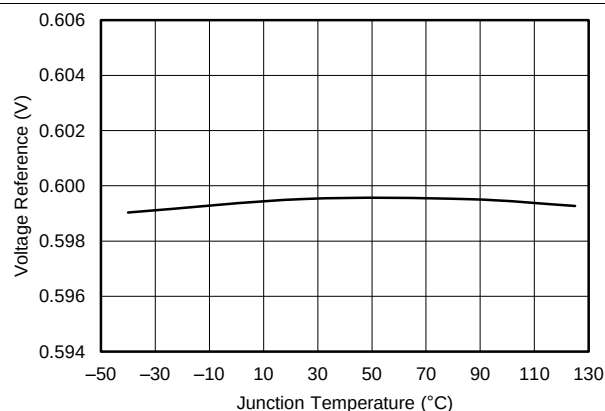


Figure 10. Voltage Reference vs Temperature

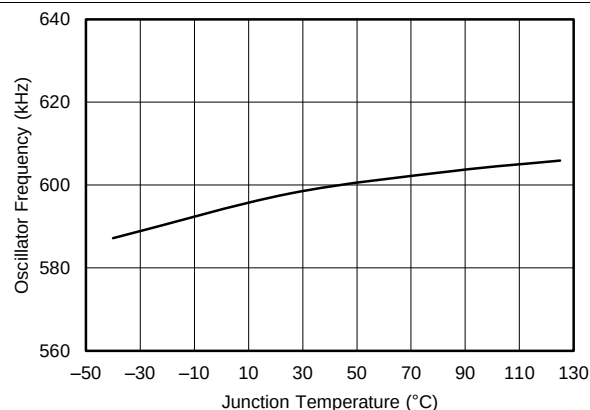


Figure 11. Oscillator Reference vs Temperature

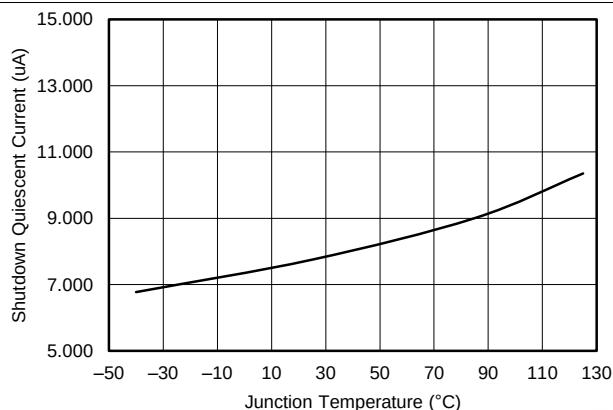
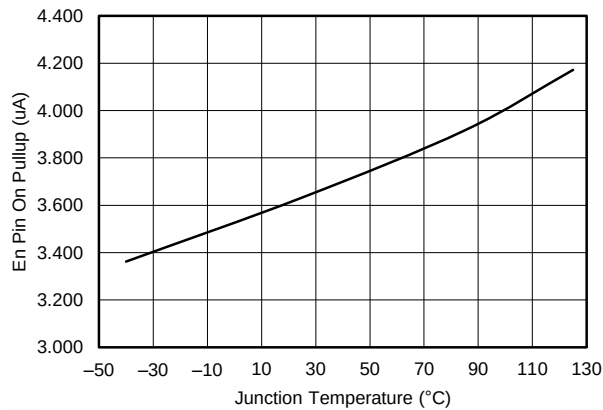
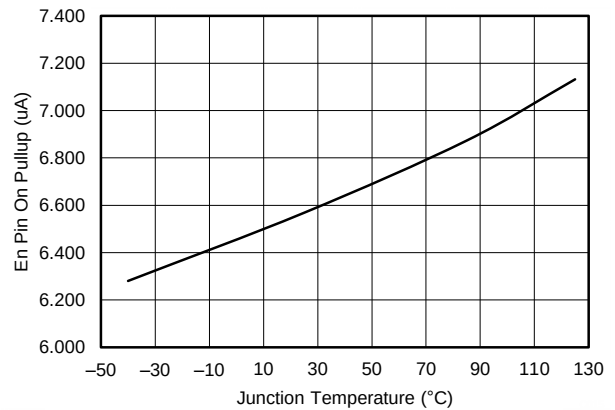
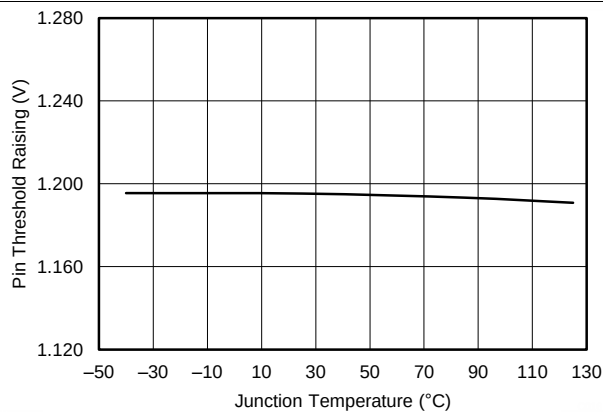
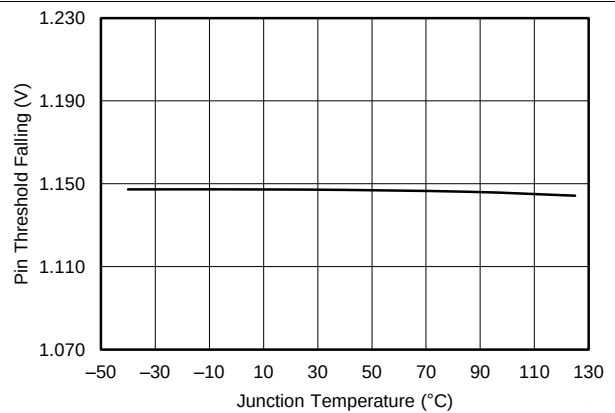
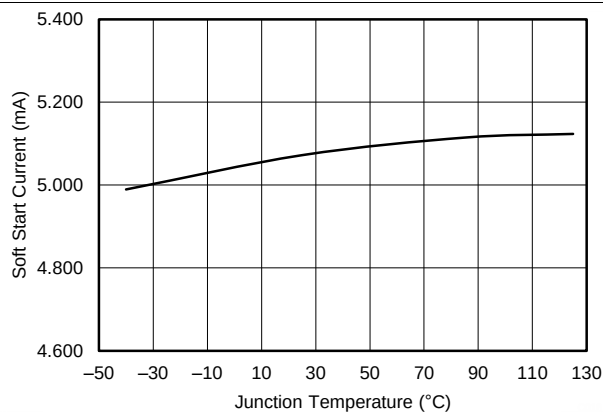
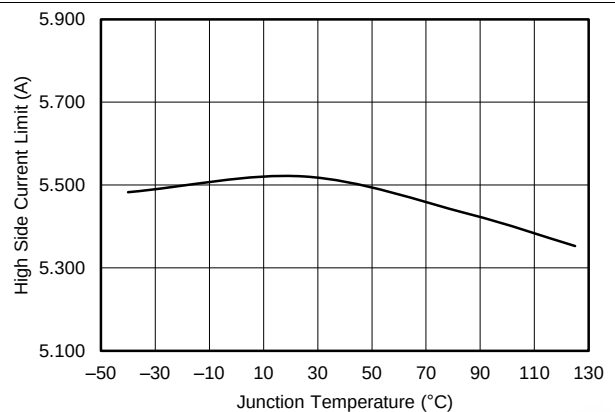


Figure 12. Shutdown Quiescent Current vs Temperature

Typical Characteristics (continued)

 $T_A = 25^\circ\text{C}$, $V_{IN} = 12\text{ V}$, $V_{OUT1} = 1.5\text{ V}$, $V_{OUT2} = 1.2\text{ V}$, $V_{OUT3} = 2.5\text{ V}$, $F_{SW} = 600\text{ kHz}$ (unless otherwise noted)

Figure 13. EN Pin Pullup Current vs Temperature, EN = 1 V

Figure 14. EN Pin Pullup Current vs Temperature, EN = 1.5 V

Figure 15. EN Pin Threshold Rising vs Temperature

Figure 16. EN Pin Threshold Falling vs Temperature

Figure 17. SS Pin Charge Current vs Temperature

Figure 18. Buck1 High-Side Current Limit vs Temperature

Typical Characteristics (continued)

$T_A = 25^\circ\text{C}$, $V_{IN} = 12\text{ V}$, $V_{OUT1} = 1.5\text{ V}$, $V_{OUT2} = 1.2\text{ V}$, $V_{OUT3} = 2.5\text{ V}$, $F_{SW} = 600\text{ kHz}$ (unless otherwise noted)

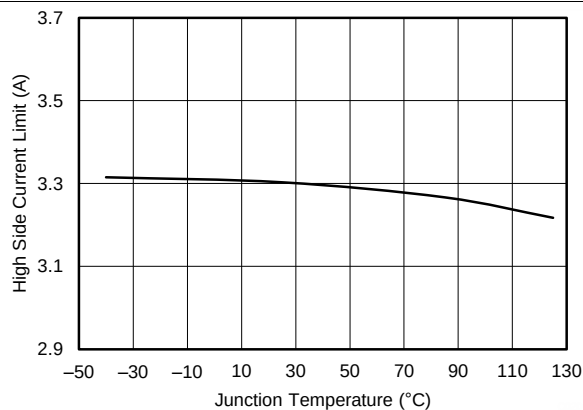


Figure 19. Buck2 High-Side Current Limit vs Temperature

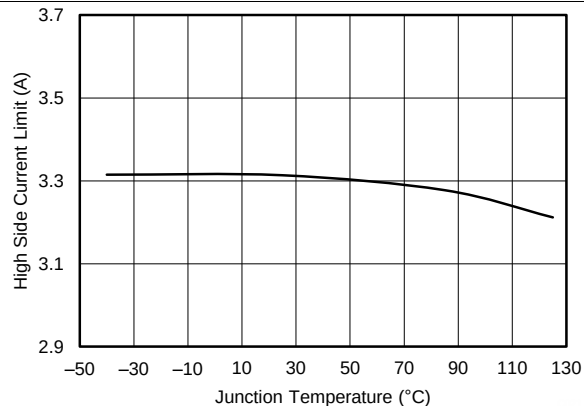


Figure 20. Buck3 High-Side Current Limit vs Temperature

9 Detailed Description

9.1 Overview

The TPS65263 is a monolithic triple synchronous step-down (buck) converter with 3-A/2-A/2-A output currents. A wide 4.5- to 18-V input supply voltage range encompasses most intermediate bus voltages operating off 5-, 9-, 12-, or 15-V power bus. The feedback voltage reference for each buck is 0.6 V. Each buck is independent with dedicated enable, soft-start and loop compensation pins.

The TPS65263 is equipped with I²C compatible bus for communication with SoC to control buck converters. Through I²C interface, SoC can enable or disable the buck converters, set output voltage and read status registers. External feedback divider resistors can set the initial start-up voltage of the buck regulators. Once the voltage identification VID DAC is updated via the I²C, output voltage of the buck regulators can be independently programmed with 7 bits VID from 0.68 to 1.95 V in 10-mV voltage step resolution. Output voltage of the buck regulators transition begins once the I²C interface receives the command for GO bit in command register.

In light loading condition, the converter will automatically operate in pulse skipping mode (PSM) to save power. The PSM can be disabled through I²C so that the converter operates at continuous current mode (CCM) at light load with a fixed frequency for optimized output ripple.

The TPS65263 implements a constant frequency, peak current mode control that simplifies external loop compensation. The device operates in fixed 600 kHz. The switch clock of buck1 is 180° out-of-phase operation from the clock of buck2 and buck3 channels to reduce input current ripple, input capacitor size and power supply induced noise.

The TPS65263 is designed for safe monotonic startup into pre-biased loads. The default start up is when VIN is typically 4.25 V. The ENx pin also can be used to adjust the input voltage UVLO with an external resistor divider. In addition, the ENx pin has an internal 3.8-μA current source, so the EN pin can be floating for automatically powering up the converters.

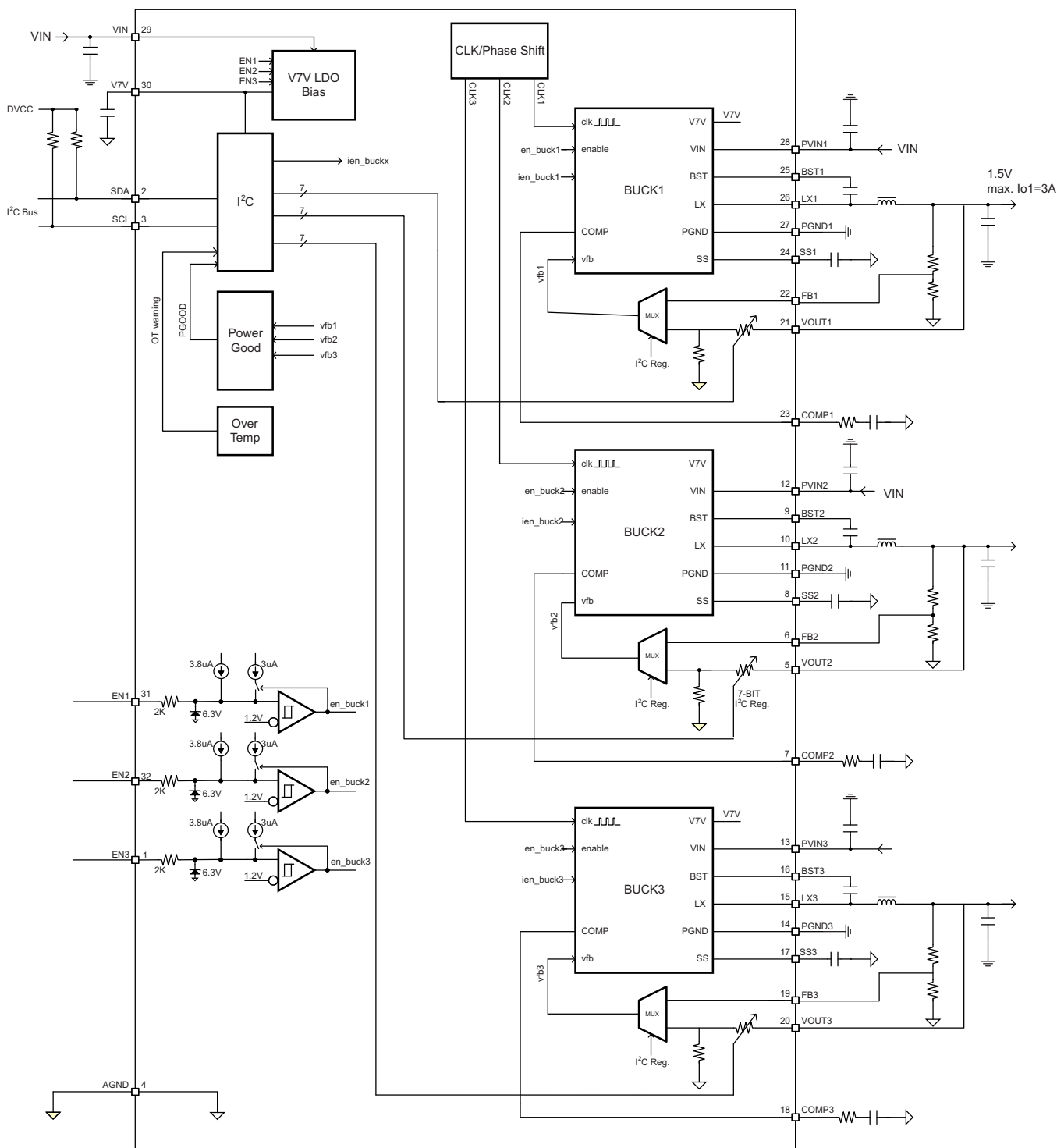
The TPS65263 reduces the external component count by integrating the bootstrap circuit. The bias voltage for the integrated high-side MOSFET is supplied by a capacitor between the BST and LX pins. A UVLO circuit monitors the bootstrap capacitor voltage VBST-VLX in each buck. When VBST-VLX voltage drops to the threshold, LX pin is pulled low to recharge the bootstrap capacitor. The TPS65263 can operate at 100% duty cycle as long as the bootstrap capacitor voltage is higher than the BOOT-LX UVLO threshold which is typically 2.1 V.

The TPS65263 has power good comparators with hysteresis, which monitor the output voltages through internal feedback voltages. I²C can read the power good status with commanding register.

The SS (soft start/tracking) pin is used to minimize inrush currents or provide power supply sequencing during power up. A small value capacitor or resistor divider is connected the pin for soft start or voltage tracking.

The TPS65263 is protected from overload and over temperature fault conditions. The converter minimizes excessive output overvoltage transients by taking advantage of the power good comparator. When the output is over, the high-side MOSFET is turned off until the internal feedback voltage is lower than 105% of the 0.6-V reference voltage. The TPS65263 implements both high-side MOSFET overload protection and bidirectional low-side MOSFET overload protections to avoid inductor current runaway. If the overcurrent condition has lasted for more than the OC wait time (0.5ms typical), the converter will shut down and re-start after the hiccup time (14ms typical). The TPS65263 shuts down if the junction temperature is higher than thermal shutdown trip point. When the junction temperature drops 20°C typically below the thermal shutdown trip point, the TPS65263 will be restarted under control of the soft start circuit automatically.

9.2 Functional Block Diagram



9.3 Feature Description

9.3.1 Adjusting the Output Voltage

The output voltage of each buck is set with a resistor divider from the output of buck to the FB pin. TI recommends to use 1% tolerance or better resistors.

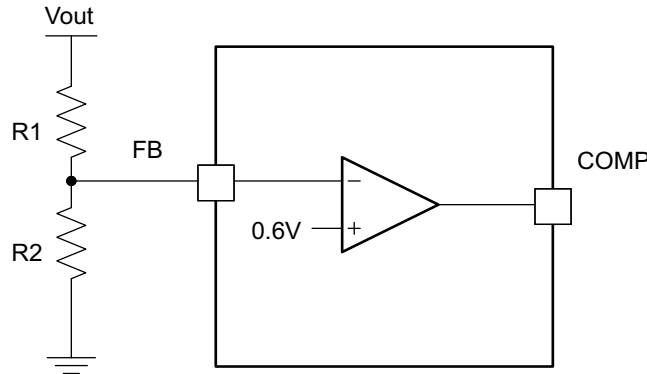


Figure 21. Voltage Divider Circuit

$$R_2 = R_1 \times \frac{0.6}{V_{out} - 0.6} \quad (1)$$

To improve efficiency at light loads consider using larger value resistors. If the values are too high, the regulator is more sensitive to noise. The recommended resistor values are shown in [Table 1](#).

Table 1. Output Resistor Divider Selection

OUTPUT VOLTAGE (V)	R1 (kΩ)	R2 (kΩ)
1	10	15
1.2	10	10
1.5	15	10
1.8	20	10
2.5	31.6	10
3.3	45.3	10
3.3	22.6	4.99
5	73.2	10
5	36.5	4.99

The output voltage of buck converter can be dynamically scaled by I²C controlled 7-bit register VOUTx_SEL. Before I²C communication, the output voltage is set with the resistor divider from the output of buck to the FB pin. When GO bit is set to 1 through I²C interface, the buck converter switches external resistor divider to the internal resistor divider as shown in [Figure 22](#). The output voltage can be selected among 128 voltages with voltage identifications (VID) shown in [Table 2](#). The output voltage range of dynamic voltage scaling is 0.68 to 1.95 V with 10-mV resolution of each voltage step.



OUT_SEL <7:0>	V _{OUT} (V)	VOUT_SEL <7:0>	V _{OUT} (V)	VOUT_SEL <7:0>	V _{OUT} (V)	VOUT_SEL <7:0>	V _{OUT} (V)
0	0.68	20	1	40	1.32	60	1.64
1	0.69	21	1.01	41	1.33	61	1.65
2	0.7	22	1.02	42	1.34	62	1.66
3	0.71	23	1.03	43	1.35	63	1.67
4	0.72	24	1.04	44	1.36	64	1.68
5	0.73	25	1.05	45	1.37	65	1.69
6	0.74	26	1.06	46	1.38	66	1.7
7	0.75	27	1.07	47	1.39	67	1.71
8	0.76	28	1.08	48	1.4	68	1.72
9	0.77	29	1.09	49	1.41	69	1.73
A	0.78	2A	1.1	4A	1.42	6A	1.74
B	0.79	2B	1.11	4B	1.43	6B	1.75
C	0.8	2C	1.12	4C	1.44	6C	1.76
D	0.81	2D	1.13	4D	1.45	6D	1.77
E	0.82	2E	1.14	4E	1.46	6E	1.78
F	0.83	2F	1.15	4F	1.47	6F	1.79
10	0.84	30	1.16	50	1.48	70	1.8
11	0.85	31	1.17	51	1.49	71	1.81
12	0.86	32	1.18	52	1.5	72	1.82
13	0.87	33	1.19	53	1.51	73	1.83
14	0.88	34	1.2	54	1.52	74	1.84
15	0.89	35	1.21	55	1.53	75	1.85
16	0.9	36	1.22	56	1.54	76	1.86
17	0.91	37	1.23	57	1.55	77	1.87
18	0.92	38	1.24	58	1.56	78	1.88
19	0.93	39	1.25	59	1.57	79	1.89
1A	0.94	3A	1.26	5A	1.58	7A	1.9
1B	0.95	3B	1.27	5B	1.59	7B	1.91
1C	0.96	3C	1.28	5C	1.6	7C	1.92
1D	0.97	3D	1.29	5D	1.61	7D	1.93

Table 2. Vout Output Voltage Setting (continued)

OUT_SEL <7:0>	V _{OUT} (V)	VOUT_SEL <7:0>	V _{OUT} (V)	VOUT_SEL <7:0>	V _{OUT} (V)	VOUT_SEL <7:0>	V _{OUT} (V)
1E	0.98	3E	1.3	5E	1.62	7E	1.94
1F	0.99	3F	1.31	5F	1.63	7F	1.95

9.3.2 Enable and Adjusting UVLO

The EN1, EN2, and EN3 pin provide electrical on and off control of the device. When the EN1, EN2, EN3 pin voltage exceeds the threshold voltage, the device starts operation. If each ENx pin voltage is pulled below the threshold voltage, the regulator stops switching and enters low Iq state.

The EN pin has an internal pullup current source, allowing the user to float the EN pin for enabling the device. If an application requires controlling the EN pin, use open drain or open collector output logic to interface with the pin.

The device implements internal UVLO circuitry on the VIN pin. The device is disabled when the VIN pin voltage falls below the internal VIN UVLO threshold. The internal VIN UVLO threshold has a hysteresis of 500 mV. If an application requires either a higher UVLO threshold on the VIN pin or a secondary UVLO on the PVINx, in split rail applications, then the ENx pin can be configured as shown in [Figure 23](#), [Figure 24](#), and [Figure 25](#). When using the external UVLO function it is recommended to set the hysteresis to be greater than 500 mV.

The EN pin has a small pullup current I_p which sets the default state of the pin to enable when no external components are connected. The pullup current is also used to control the voltage hysteresis for the UVLO function since it increases by I_h once the EN pin crosses the enable threshold. The UVLO thresholds can be calculated using [Equation 2](#) and [Equation 3](#).

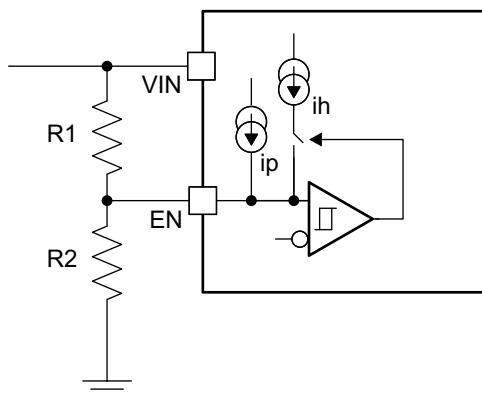
$$R_1 = \frac{V_{START} \left(\frac{V_{ENFALLING}}{V_{ENRISING}} \right) - V_{STOP}}{I_p \left(1 - \frac{V_{ENFALLING}}{V_{ENRISING}} \right) + I_h} \quad (2)$$

$$R_2 = \frac{R_1 \times V_{ENFALLING}}{V_{STOP} - V_{ENFALLING} + R_1 (I_h + I_p)}$$

where

- I_h = 3 μA
- I_p = 3.8 μA
- V_{ENRISING} = 1.2 V
- V_{ENFALLING} = 1.15 V

(3)


Figure 23. Adjustable VIN UVLO

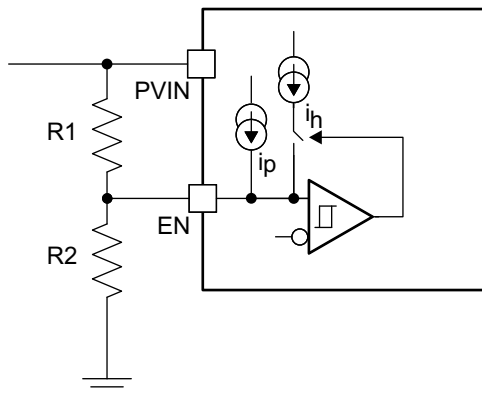


Figure 24. Adjustable PVIN UVLO, VIN > 4.5 V

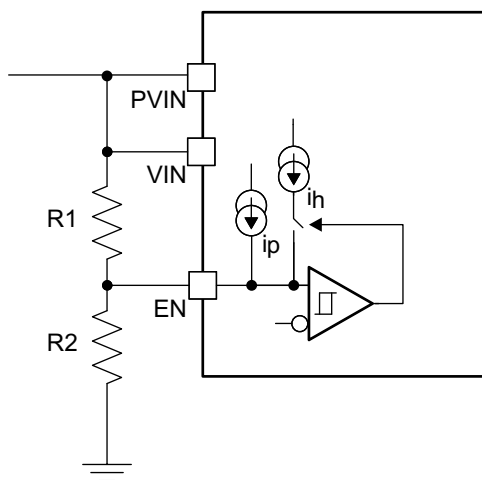


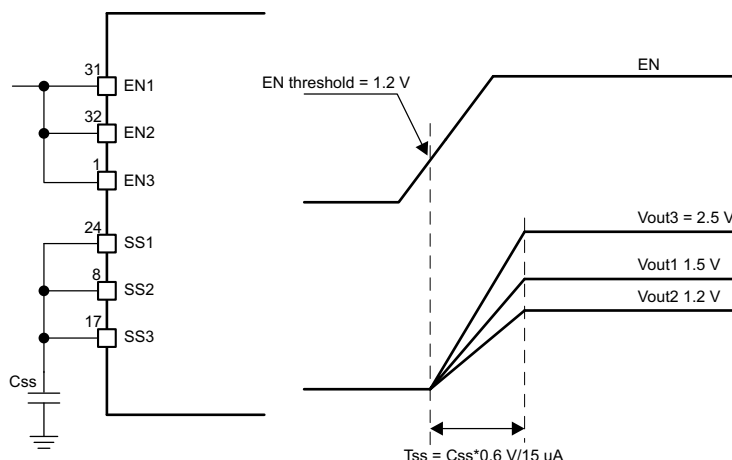
Figure 25. Adjustable VIN and PVIN UVLO

9.3.3 Soft-Start Time

The voltage on the respective SS pin controls the start-up of buck output. When the voltage on the SS pin is less than the internal 0.6-V reference, The TPS65263 regulates the internal feedback voltage to the voltage on the SS pin instead of 0.6 V. The SS pin can be used to program an external soft-start function or to allow output of buck to track another supply during start-up. The device has an internal pullup current source of 5 μ A (typical) that charges an external soft-start capacitor to provide a linear ramping voltage at SS pin. The TPS65263 regulates the internal feedback voltage to the voltage on the SS pin, allowing VOUT to rise smoothly from 0V to its regulated voltage without inrush current. The soft-start time can be calculated approximately by [Equation 4](#).

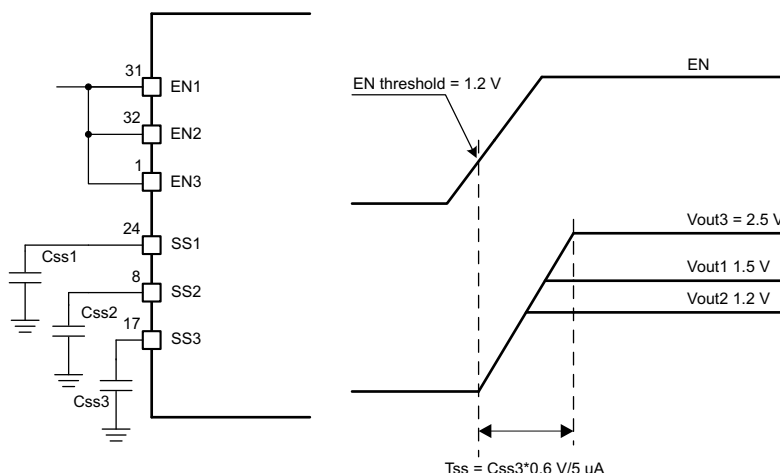
$$T_{ss}(ms) = \frac{C_{ss}(nF) \times V_{ref}(V)}{I_{ss}(\mu A)} \quad (4)$$

Many of the common power supply sequencing methods can be implemented using the SSx and ENx pins. [Figure 26](#) shows the method implementing ratiometric sequencing by connecting the SSx pins of three buck channels together. The regulator outputs ramp up and reach regulation at the same time. When calculating the soft-start time, the pullup current source must be tripled in [Equation 4](#).


Figure 26. Ratiometric Power-Up Using SSx Pins

Simultaneous power supply sequencing can be implemented by connecting capacitor to SSx pin, shown in [Figure 27](#). Using [Equation 4](#) and [Equation 5](#), the capacitors can be calculated.

$$\frac{C_{ss1}}{V_{out1}} = \frac{C_{ss2}}{V_{out2}} = \frac{C_{ss3}}{V_{out3}} \quad (5)$$


Figure 27. Simultaneous Startup Sequence Using SSx Pins

9.3.4 Power-Up Sequencing

The TPS65263 has dedicated enable pin and soft-start pin for each converter. The converter enable pins are biased by a current source that allows for easy sequencing by the addition of an external capacitor. Disabling the converter with an active pull-down transistor on the ENs pin allows for a predictable power-down timing operation. [Figure 28](#) shows the timing diagram of a typical buck power-up sequence with connecting a capacitor at ENx pin.

A typical 1.4-μA current is charging ENx pin from input supply. When ENx pin voltage rise to typical 0.4 V, the internal V7V LDO turns on. A 3.8-μA pullup current is sourcing ENx. After ENx pin voltage reaches to ENx enabling threshold, 3-μA hysteresis current sources to the pin to improve noise sensitivity. The internal soft-start comparator compares SS pin voltage to 1.2 V. When SS pin voltage ramps up to 1.2 V, PGOOD monitor is enabled. After PGOOD deglitch time, PGOOD is deasserted. SS pin voltage eventually is clamped around 2.1 V.

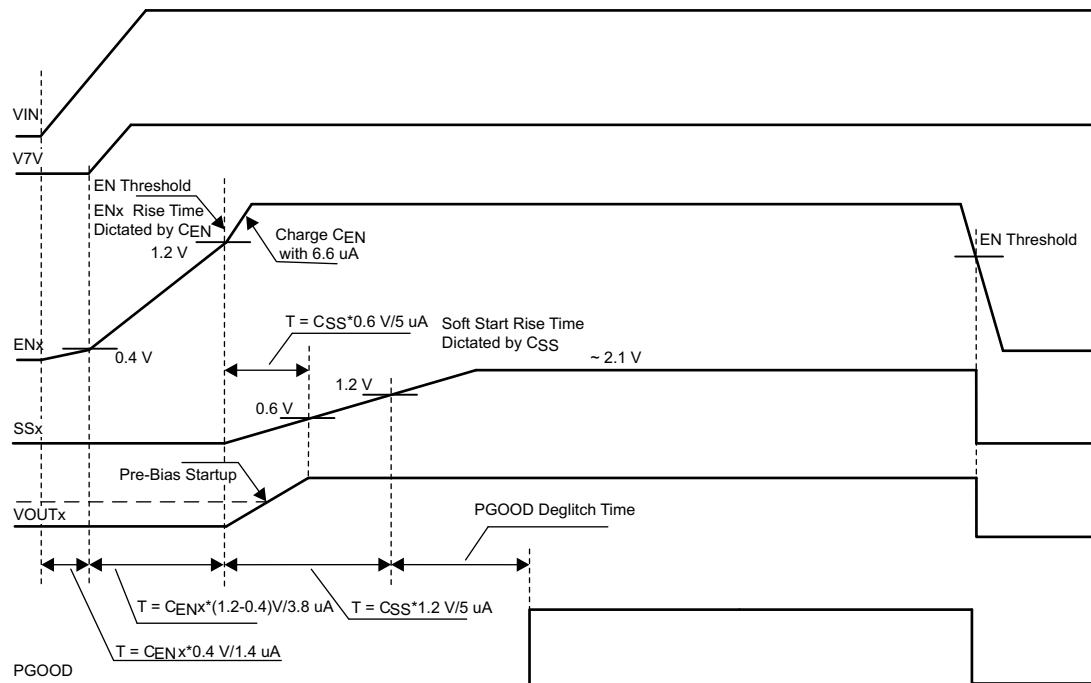


Figure 28. Startup Power Sequence

9.3.5 V7V Low Dropout Regulator and Bootstrap

Power for the high-side and low-side MOSFET drivers and most other internal circuitry is derived from the V7V pin. The internal built-in low dropout linear regulator (LDO) supplies 6.3 V (typical) from VIN to V7V. A 1-μF ceramic capacitor should be connected from V7V pin to power ground.

If the input voltage, VIN decreases to UVLO threshold voltage, the UVLO comparator detects V7V pin voltage and forces the converter off.

Each high-side MOSFET driver is biased from the floating bootstrap capacitor CB, shown in [Figure 29](#), which is normally recharged during each cycle through an internal low-side MOSFET or the body diode of low-side MOSFET when the high-side MOSFET turns off. The boot capacitor is charged when the BST pin voltage is less than VIN and BST-LX voltage is below regulation. The recommended value of this ceramic capacitor is 47 nF. TI recommends a ceramic capacitor with an X7R or X5R grade dielectric with a voltage rating of 10 V or higher because of the stable characteristics over temperature and voltage. Each low-side MOSFET driver is powered from V7V pin directly.

To improve drop out, the device is designed to operate at 100% duty cycle as long as the BST to LX pin voltage is greater than the BST-LX UVLO threshold, which is typically 2.1 V. When the voltage between BST and LX drops below the BST-LX UVLO threshold, the high-side MOSFET is turned off and the low-side MOSFET is turned on allowing the boot capacitor to be recharged.

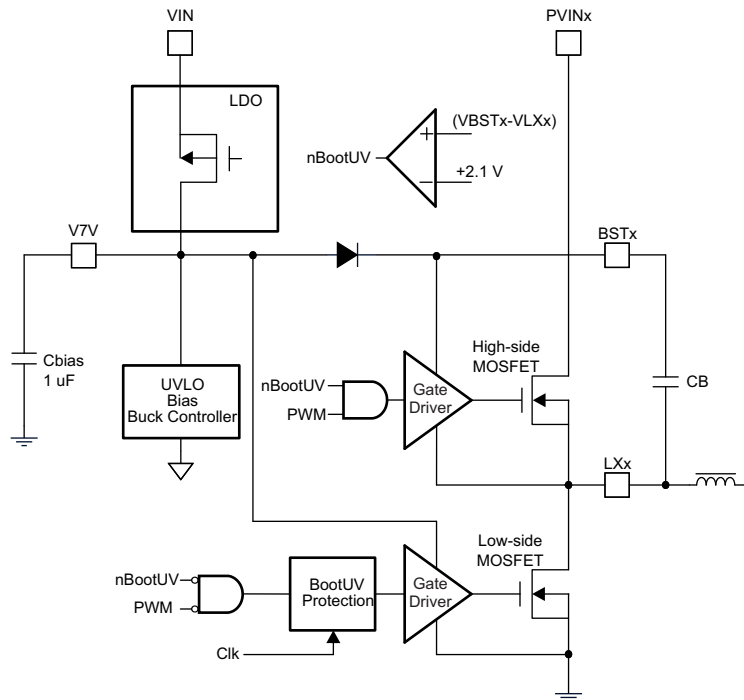


Figure 29. V7V Linear Dropout Regulator and Bootstrap Voltage Diagram

9.3.6 Out-of-Phase Operation

To reduce input ripple current, the switch clock of buck1 is 180° out-of-phase from the clock of buck2 and buck3. This enables the system having less input current ripple to reduce input capacitors' size, cost, and EMI.

9.3.7 Output Overvoltage Protection (OVP)

The device incorporates an output OVP circuit to minimize output voltage overshoot. When the output is overloaded, the error amplifier compares the actual output voltage to the internal reference voltage. If the FB pin voltage is lower than the internal reference voltage for a considerable time, the output of the error amplifier demands maximum output current. Once the condition is removed, the regulator output rises and the error amplifier output transitions to the steady state voltage. In some applications with small output capacitance, the load can respond faster than the error amplifier. This leads to the possibility of an output overshoot. Each buck compares the FB pin voltage to the OVP threshold. If the FB pin voltage is greater than the OVP threshold, the high-side MOSFET is turned off preventing current from flowing to the output and minimizing output overshoot. When the FB voltage drops lower than the OVP threshold, the high-side MOSFET turns on at the next clock cycle.

9.3.8 Pulse Skipping Mode (PSM)

The TPS65263 can enter high-efficiency PSM operation at light load current. To disable PSM operation, set VOUTx_COM registers' bit 1 to 1 through I²C interface.

When a controller is enabled for PSM operation, the peak inductor current is sensed and compared with 230-mA current typically. Since the integrated current comparator catches the peak inductor current only, the average load current entering PSM varies with the applications and external output filters. In PSM, the sensed peak inductor current is clamped at 230 mA, shown in [Figure 30](#).

When a controller operates in PSM, the inductor current is not allowed to reverse. The reverse current comparator turns off the low-side MOSFET when the inductor current reaches zero, preventing it from reversing and going negative.

Due to the delay in the circuit and current comparator t_{dly} (typical 50 nS at $V_{in} = 12$ V), the real peak inductor current threshold to turn off high-side power MOSFET could shift higher depending on inductor inductance and input/output voltages. The threshold of peak inductor current to turn off high-side power MOSFET can be calculated by Equation 6.

$$I_{L_PEAK} = 230\text{mA} + \frac{v_{in} - v_{out}}{L} \times t_{dly} \quad (6)$$

When the charge accumulated on V_{out} capacitor is more than loading need, COMP pin voltage drops to low voltage driven by error amplifier. There is an internal comparator at COMP pin. If comp voltage is lower than 0.35 V, power stage stops switching to save power.

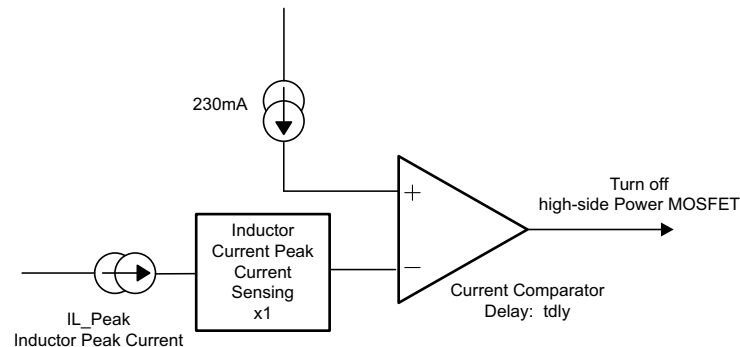


Figure 30. PSM Current Comparator

9.3.9 Slope Compensation

In order to prevent the sub-harmonic oscillations when the device operates at duty cycles greater than 50%, the TPS65263 adds built-in slope compensation, which is a compensating ramp to the switch current signal.

9.3.10 Overcurrent Protection

The device is protected from overcurrent conditions by cycle-by-cycle current limiting on both the high-side MOSFET and the low-side MOSFET.

9.3.10.1 High-Side MOSFET Overcurrent Protection

The device implements current mode control which uses the COMP pin voltage to control the turn off of the high-side MOSFET and the turn on of the low-side MOSFET on a cycle by cycle basis. Each cycle the switch current and the current reference generated by the COMP pin voltage are compared, when the peak switch current intersects the current reference, the high-side switch is turned off.

9.3.10.2 Low-Side MOSFET Overcurrent Protection

While the low-side MOSFET is turned on, its conduction current is monitored by the internal circuitry. During normal operation the low-side MOSFET sources current to the load. At the end of every clock cycle, the low-side MOSFET sourcing current is compared to the internally set low-side sourcing current limit. If the low-side sourcing current is exceeded, the high-side MOSFET is not turned on and the low-side MOSFET stays on for the next cycle. The high-side MOSFET is turned on again when the low-side current is below the low-side sourcing current limit at the start of a cycle.

The low-side MOSFET may also sink current from the load. If the low-side sinking current limit is exceeded, the low-side MOSFET is turned off immediately for the rest of that clock cycle. In this scenario both MOSFETs are off until the start of the next cycle.

Furthermore, if an output overload condition (as measured by the COMP pin voltage) has lasted for more than the hiccup wait time which is programmed for 0.5 ms (typical) shown in Figure 31, the device will shut down itself and restart after the hiccup time of 14 ms (typical). The hiccup mode helps to reduce the device power dissipation under severe overcurrent condition.

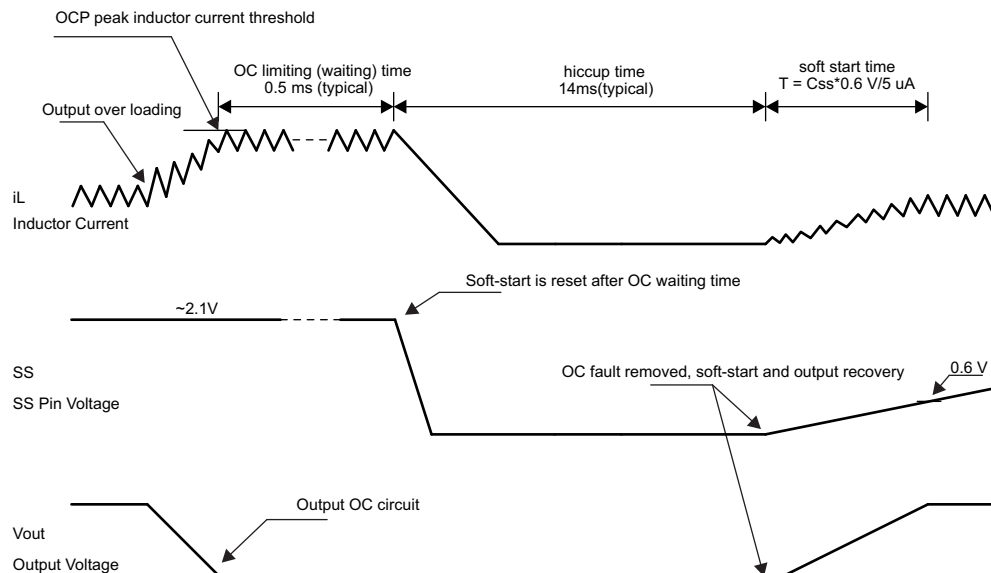


Figure 31. Overcurrent Protection

9.3.11 Power Good

The power good indicator for each buck channel can be read back through I²C.

When feedback voltage of the buck is between 95% (rising) and 105% (falling) of the internal voltage reference, the bit0, bit1 and bit2 in SYS_STATUS (address 0x06H) present the feedback voltage in regulation (logic 1) for buck1, buck2 and buck3 respectively. When feedback voltage of the buck is lower than 92.5% (falling) or greater than 107.5% (rising) of the nominal internal reference voltage, the bit0, bit1 and bit2 in SYS_STATUS (address 0x06H) present the feedback voltage beyond regulation (logic 0) for buck1, buck2 and buck3 respectively.

9.3.12 Thermal Shutdown

The internal thermal shutdown circuitry forces the device to stop switching if the junction temperature exceeds 160°C typically. The device reinitiates the power up sequence when the junction temperature drops below 140°C typically.

9.4 Device Functional Modes

9.4.1 Serial Interface Description

I²C is a 2-wire serial interface developed by NXP™ Semiconductors (see I²C-Bus Specification, Version 2.1, January 2000). The bus consists of a data line (SDA) and a clock line (SCL) with pullup structures. When the bus is idle, both SDA and SCL lines are pulled high. All the I²C-compatible devices connect to the I²C bus through open drain I/O pins, SDA and SCL. A master device, usually a microcontroller or a digital signal processor, controls the bus. The master is responsible for generating the SCL signal and device addresses. The master also generates specific conditions that indicate the START and STOP of data transfer. A slave device receives and/or transmits data on the bus under control of the master device.

The TPS65263 device works as a slave and supports the following data transfer modes, as defined in the I²C-Bus Specification: standard mode (100 kbps), and fast mode (400 kbps). The interface adds flexibility to the power supply solution, enabling most functions to be programmed to new values depending on the instantaneous application requirements. Register contents remain intact as long as supply voltage remains above 4.25 V (typical).

The data transfer protocol for standard and fast modes is exactly the same, therefore, they are referred to as F/S-mode in this document. The TPS65263 device supports 7-bit addressing. Ten-bit addressing and general call address are not supported.

Device Functional Modes (continued)

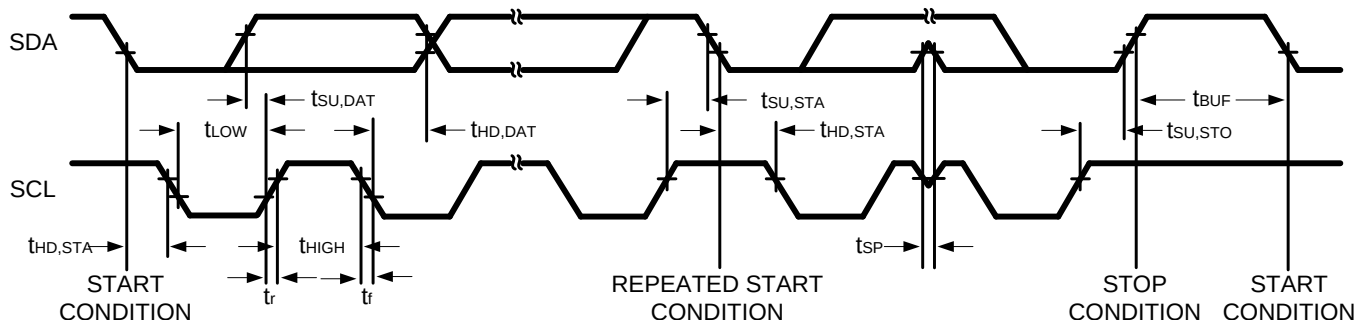


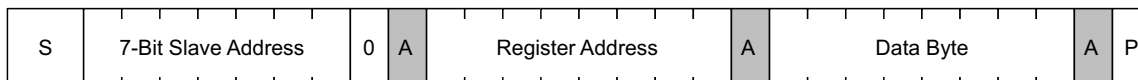
Figure 32. I²C Interface Timing Diagram

9.4.2 I²C Update Sequence

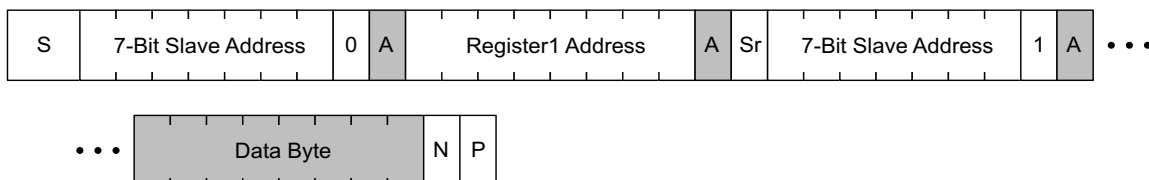
The TPS65263 requires a start condition, a valid I²C address, a register address byte, and a data byte for a single update. After the receipt of each byte, TPS65263 device acknowledges by pulling the SDA line low during the high period of a single clock pulse. A valid I²C address selects the TPS65263. TPS65263 performs an update on the falling edge of the LSB byte.

When the TPS65263 is in hardware shutdown (EN1, EN2, and EN3 pin tied to ground) the device cannot be updated through the I²C interface. Conversely, the I²C interface is fully functional during software shutdown (EN1, EN2, and EN3 bit = 0).

I²C Write Data Format



I²C Read Data Format



A: Acknowledge

N: Not Acknowledge

S: Start

P: Stop

Sr: Repeated Start

 System Host

 Chip

Figure 33. I²C Write and Read Data Format

9.5 Register Maps

9.5.1 Register Description

Register descriptions are shown in the following tables.

Table 3. Register Addresses

NAME	BITS	ADDRESS
VOUT1_SEL	8	0x00H
VOUT2_SEL	8	0x01H
VOUT3_SEL	8	0x02H
VOUT1_COM	8	0x03H
VOUT2_COM	8	0x04H
VOUT3_COM	8	0x05H
SYS_STATUS	8	0x06H

9.5.2 VOUT1_SEL: Vout1 Voltage Selection Register (offset = 0x00H)

Figure 34. VOUT1_SEL

7	6	5	4	3	2	1	0
Vout1_Bit7	Vout1_Bit6	Vout1_Bit5	Vout1_Bit4	Vout1_Bit3	Vout1_Bit2	Vout1_Bit1	Vout1_Bit0
R/W							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 4. VOUT1_SEL Field Descriptions

Bit	Field	Type	Reset	Description
7	Vout1_Bit7	R/W		GO bit, must set to 1 to enable I ² C controlled VID voltages (default 0)
6	Vout1_Bit6	R/W		128 voltage selections with 7-bits control (default 0) Voltage range: 0.68 to 1.95 V Voltage step resolution: 10 mV 0x00H: Vout1 = 0.68 V; 0x7FH: Vout1 = 1.95 V
5	Vout1_Bit5			
4	Vout1_Bit4			
3	Vout1_Bit3			
2	Vout1_Bit2			
1	Vout1_Bit1			
0	Vout1_Bit0			

9.5.3 VOUT2_SEL: Vout2 Voltage Selection Register (offset = 0x01H)

Figure 35. VOUT2_SEL

7	6	5	4	3	2	1	0
Vout2_Bit7	Vout2_Bit6	Vout2_Bit5	Vout2_Bit4	Vout2_Bit3	Vout2_Bit2	Vout2_Bit1	Vout2_Bit0
R/W							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 5. VOUT2_SEL Field Descriptions

Bit	Field	Type	Reset	Description
7	Vout2_Bit7	R/W		GO bit, must set to 1 to enable I ² C controlled VID voltages (default 0)
6	Vout2_Bit6	R/W		128 voltage selections with 7-bits control (default 0) Voltage range: 0.68 to 1.95 V Voltage step resolution: 10 mV 0x00H: Vout2 = 0.68 V; 0x7FH: Vout2 = 1.95 V
5	Vout2_Bit5			
4	Vout2_Bit4			
3	Vout2_Bit3			
2	Vout2_Bit2			
1	Vout2_Bit1			
0	Vout2_Bit0			

9.5.4 VOUT3_SEL: Vout3 Voltage Selection Register (offset = 0x02H)

Figure 36. VOUT3_SEL

7	6	5	4	3	2	1	0
Vout3_Bit7	Vout3_Bit6	Vout3_Bit5	Vout3_Bit4	Vout3_Bit3	Vout3_Bit2	Vout3_Bit1	Vout3_Bit0
R/W							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 6. VOUT3_SEL Field Descriptions

Bit	Field	Type	Reset	Description
7	Vout3_Bit7	R/W		GO bit, must set to 1 to enable I ² C controlled VID voltages (default 0)
6	Vout3_Bit6	R/W		128 voltage selections with 7-bits control (default 0) Voltage range: 0.68 to 1.95 V Voltage step resolution: 10 mV 0x00H: Vout3 = 0.68 V; 0x7FH: Vout3 = 1.95 V
5	Vout3_Bit5			
4	Vout3_Bit4			
3	Vout3_Bit3			
2	Vout3_Bit2			
1	Vout3_Bit1			
0	Vout3_Bit0			

9.5.5 VOUT1_COM: Buck1 Command Register (offset = 0x03H)

Figure 37. VOUT1_COM

7	6	5	4	3	2	1	0
N/A	SR3	SR2	SR1	N/A	N/A	Mode1	nEN1
R/W							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 7. VOUT1_COM Field Descriptions

Bit	Field	Type	Reset	Description
7	N/A	R/W		Not used (default 0)
6	SR3	R/W		Vout1 VID voltage transition slew rate control (default 0) 000: 10 mV/cycle; 001: 10 mV/2 cycles; 010: 10 mV/4 cycles; 011: 10 mV/8 cycles; 100: 10 mV/16 cycles; 101: 10 mV/32 cycles; 110: 10 mV/64 cycles; 111: 10 mV/128 cycles
5	SR2	R/W		
4	SR1	R/W		
3	N/A	R/W		Not used (default 0)
2	N/A	R/W		Not used (default 0)
1	Mode1	R/W		0: Enable buck1 PSM operation at light load (default); 1: Forced buck1 PWM mode operation
0	nEN1	R/W		0: Enable buck1 (default); 1: Disable buck1

9.5.6 VOUT2_COM: Buck2 Command Register (offset = 0x04H)

Figure 38. VOUT2_COM

7	6	5	4	3	2	1	0
N/A	SR3	SR2	SR1	N/A	N/A	Mode2	nEN2
R/W							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 8. VOUT2_COM Field Descriptions

Bit	Field	Type	Reset	Description
7	N/A	R/W		Not used (default 0)
6	SR3	R/W		Vout2 VID voltage transition slew rate control (default 0) 000: 10 mV/cycle; 001: 10 mV/2 cycles; 010: 10 mV/4 cycles; 011: 10 mV/8 cycles; 100: 10 mV/16 cycles; 101: 10 mV/32 cycles; 110: 10 mV/64 cycles; 111: 10 mV/128 cycles
5	SR2	R/W		
4	SR1	R/W		
3	N/A	R/W		Not used (default 0)
2	N/A	R/W		Not used (default 0)
1	Mode2	R/W		0: Enable buck2 PSM operation at light load (default); 1: Forced buck2 PWM mode operation
0	nEN2	R/W		0: Enable buck2 (default); 1: Disable buck2

9.5.7 VOUT3_COM: Buck3 Command Register (offset = 0x05H)

Figure 39. VOUT3_COM

7	6	5	4	3	2	1	0
N/A	SR3	SR2	SR1	N/A	N/A	Mode3	nEN3
R/W							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 9. VOUT3_COM Field Descriptions

Bit	Field	Type	Reset	Description
7	N/A	R/W		Not used (default 0)
6	SR3	R/W		Vout3 VID voltage transition slew rate control. 000: 10 mV/cycle; 001: 10 mV/2 cycles; 010: 10 mV/4 cycles; 011: 10 mV/8 cycles; 100: 10 mV/16 cycles; 101: 10 mV/32 cycles; 110: 10 mV/64 cycles; 111: 10 mV/128 cycles
5	SR2	R/W		
4	SR1	R/W		
3	N/A	R/W		Not used (default 0)
2	N/A	R/W		Not used (default 0)
1	Mode3	R/W		0: Enable buck3 PSM operation at light load (default); 1: Forced buck3 PWM mode operation
0	nEN3	R/W		0: Enable buck3 (default); 1: Disable buck3

9.5.8 SYS_STATUS: System Status Register (offset = 0x06H)

Figure 40. SYS_STATUS

7	6	5	4	3	2	1	0
OTP	OC3	OC2	OC1	OTW	PGOOD3	PGOOD2	PGOOD1
R							

LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

Table 10. SYS_STATUS Field Descriptions

Bit	Field	Type	Reset	Description
7	OTP	R		0: Die overtemperature protection is not triggered (default); 1: Die temperature over 160°C, which triggers overtemperature protection.
6	OC3	R		0: Buck3 current not beyond the current limit (default); 1: Buck3 overcurrent limiting and hiccup protection is triggered.
5	OC2	R		0: Buck2 current not beyond the current limit (default); 1: Buck2 overcurrent limiting and hiccup protection is triggered.
4	OC1	R		0: Buck1 current not beyond the current limit (default); 1: Buck1 overcurrent limiting and hiccup protection is triggered.
3	OTW	R		0: Die temperature below 125°C (default); 1: Die temperature over 125°C.
2	PGOOD3	R		0: Vout3 not in power good monitor's range (default); 1: Vout3 in power good monitor's range.
1	PGOOD2	R		0: Vout2 not in power good monitor's range (default); 1: Vout2 in power good monitor's range.
0	PGOOD1	R		0: Vout1 not in power good monitor's range (default); 1: Vout1 in power good monitor's range.

10 Application and Implementation

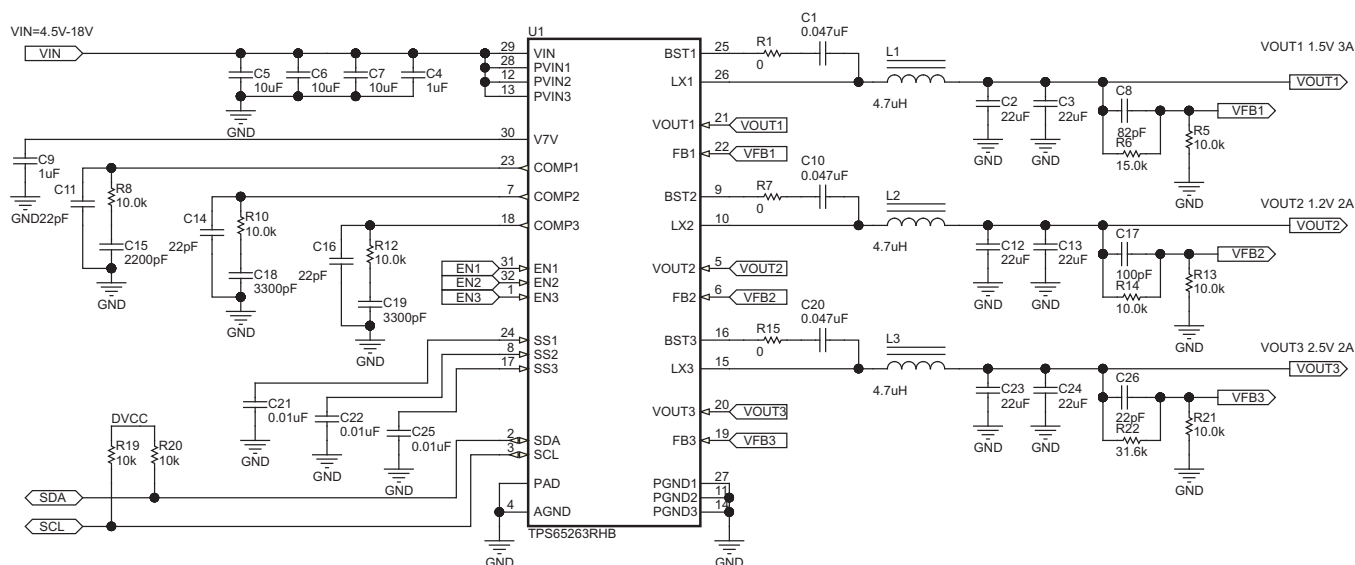
NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

10.1 Application Information

The device is triple synchronous step down dc/dc converter with I²C interface. It is typically used to convert a higher dc voltage to lower dc voltages with continuous available output current of 3 A / 2 A / 2 A. The following design procedure can be used to select component values for the TPS65263. This section presents a simplified discussion of the design process.

10.2 Typical Application



10.2.1 Design Requirements

This example details the design of triple synchronous step-down converter. A few parameters must be known in order to start the design process. These parameters are typically determined at the system level. For this example, start with the following known parameters:

Table 11. Design Parameters

PARAMETER	VALUE
Vout1	1.5 V
Iout1	3 A
Vout2	1.2 V
Iout2	2 A
Vout3	2.5 V
Iout3	2 A
Transient response 1-A load step	±5%
Input voltage	12 V normal, 4.5 to 18 V
Output voltage ripple	±1%
Switching frequency	600 kHz

10.2.2 Detailed Design Procedure

10.2.2.1 Output Inductor Selection

To calculate the value of the output inductor, use [Equation 7](#). LIR is a coefficient that represents the amount of inductor ripple current relative to the maximum output current. The inductor ripple current is filtered by the output capacitor. Therefore, choosing high inductor ripple currents impact the selection of the output capacitor since the output capacitor must have a ripple current rating equal to or greater than the inductor ripple current. In general, the inductor ripple value is at the discretion of the designer; however, LIR is normally from 0.1 to 0.3 for the majority of applications.

$$L = \frac{V_{inmax} - V_{out}}{I_o \times LIR} \times \frac{V_{out}}{V_{inmax} \times f_{sw}} \quad (7)$$

For the output filter inductor, it is important that the RMS current and saturation current ratings not be exceeded. The RMS and peak inductor current can be found from [Equation 9](#) and [Equation 10](#).

$$I_{ripple} = \frac{V_{inmax} - V_{out}}{L} \times \frac{V_{out}}{V_{inmax} \times f_{sw}} \quad (8)$$

$$I_{Lrms} = \sqrt{I_o^2 + \frac{\left(\frac{V_{out} \times (V_{inmax} - V_{out})}{V_{inmax} \times L \times f_{sw}} \right)^2}{12}} \quad (9)$$

$$I_{Lpeak} = I_{out} + \frac{I_{ripple}}{2} \quad (10)$$

The current flowing through the inductor is the inductor ripple current plus the output current. During power up, faults or transient load conditions, the inductor current can increase above the calculated peak inductor current level calculated above. In transient conditions, the inductor current can increase up to the switch current limit of the device. For this reason, the most conservative approach is to specify an inductor with a saturation current rating equal to or greater than the switch current limit rather than the peak inductor current.

10.2.2.2 Output Capacitor Selection

There are three primary considerations for selecting the value of the output capacitor. The output capacitor determines the modulator pole, the output voltage ripple, and how the regulator responds to a large change in load current. The output capacitance needs to be selected based on the most stringent of these three criteria.

The desired response to a large change in the load current is the first criteria. The output capacitor needs to supply the load with current when the regulator cannot. This situation would occur if there are desired hold-up times for the regulator where the output capacitor must hold the output voltage above a certain level for a specified amount of time after the input power is removed. The regulator is also temporarily not able to supply sufficient output current if there is a large, fast increase in the current needs of the load such as a transition from no load to full load. The regulator usually needs two or more clock cycles for the control loop to see the change in load current and output voltage and adjust the duty cycle to react to the change. The output capacitor must be sized to supply the extra current to the load until the control loop responds to the load change. The output capacitance must be large enough to supply the difference in current for 2 clock cycles while only allowing a tolerable amount of droop in the output voltage. [Equation 11](#) shows the minimum output capacitance necessary to accomplish this.

$$C_o = \frac{2 \times \Delta I_{out}}{f_{sw} \times \Delta V_{out}} \quad (11)$$

Where ΔI_{out} is the change in output current, f_{sw} is the regulators switching frequency and ΔV_{out} is the allowable change in the output voltage.

[Equation 12](#) calculates the minimum output capacitance needed to meet the output voltage ripple specification. Where f_{sw} is the switching frequency, V_{ripple} is the maximum allowable output voltage ripple, and I_{ripple} is the inductor ripple current.

$$C_o > \frac{1}{8 \times f_{sw}} \times \frac{1}{\frac{V_{oripple}}{I_{oripple}}} \quad (12)$$

Equation 13 calculates the maximum ESR an output capacitor can have to meet the output voltage ripple specification.

$$R_{esr} < \frac{V_{oripple}}{I_{oripple}} \quad (13)$$

Additional capacitance de-ratings for aging, temperature and DC bias should be factored in which increases this minimum value. Capacitors generally have limits to the amount of ripple current they can handle without failing or producing excess heat. An output capacitor that can support the inductor ripple current must be specified. Some capacitor data sheets specify the root mean square (RMS) value of the maximum ripple current. **Equation 14** can be used to calculate the RMS ripple current the output capacitor needs to support.

$$I_{corms} = \frac{V_{out} \times (V_{inmax} - V_{out})}{\sqrt{12} \times V_{inmax} \times L \times f_{sw}} \quad (14)$$

10.2.2.3 Input Capacitor Selection

The TPS65263 requires a high quality ceramic, type X5R or X7R, input decoupling capacitor of at least 10 µF of effective capacitance on the PVIN input voltage pins. In some applications additional bulk capacitance may also be required for the PVIN input. The effective capacitance includes any DC bias effects. The voltage rating of the input capacitor must be greater than the maximum input voltage. The capacitor must also have a ripple current rating greater than the maximum input current ripple of The TPS65263. The input ripple current can be calculated using **Equation 15**.

$$I_{inrms} = I_{out} \times \sqrt{\frac{V_{out}}{V_{inmin}} \times \frac{(V_{inmin} - V_{out})}{V_{inmin}}} \quad (15)$$

The value of a ceramic capacitor varies significantly over temperature and the amount of DC bias applied to the capacitor. The capacitance variations due to temperature can be minimized by selecting a dielectric material that is stable over temperature. X5R and X7R ceramic dielectrics are usually selected for power regulator capacitors because they have a high capacitance to volume ratio and are fairly stable over temperature. The output capacitor must also be selected with the DC bias taken into account. The capacitance value of a capacitor decreases as the DC bias across a capacitor increases. The input capacitance value determines the input ripple voltage of the regulator. The input voltage ripple can be calculated using **Equation 16**.

$$\Delta V_{in} = \frac{I_{outmax} \times 0.25}{C_{in} \times f_{sw}} \quad (16)$$

10.2.2.4 Loop Compensation

The TPS65263 incorporates a peak current mode control scheme. The error amplifier is a trans-conductance amplifier with a gain of 300 µS. A typical type II compensation circuit adequately delivers a phase margin between 60° and 90°. C_b adds a high frequency pole to attenuate high frequency noise when needed. To calculate the external compensation components, follow the following steps.

1. Select switching frequency f_{sw} that is appropriate for application depending on L and C sizes, output ripple, EMI, and etc. Switching frequency between 500 kHz to 1 MHz gives best trade-off between performance and cost. To optimize efficiency, lower switching frequency is desired.
2. Set up cross over frequency, f_c , which is typically between 1/5 and 1/20 of f_{sw} .
3. R_c can be determined by

$$R_c = \frac{2\pi \times f_c \times V_o \times C_o}{G_{m-EA} \times V_{ref} \times G_{m-PS}} \quad (17)$$

4. Calculate CC by placing a compensation zero at or before the dominant pole $\left(f_p = \frac{1}{C_o \times R_L \times 2\pi} \right)$.

$$C_C = \frac{R_L \times C_O}{R_C} \quad (18)$$

5. Optional C_b can be used to cancel the zero from the ESR associated with C_O .

$$C_b = \frac{R_{ESR} \times C_O}{R_C} \quad (19)$$

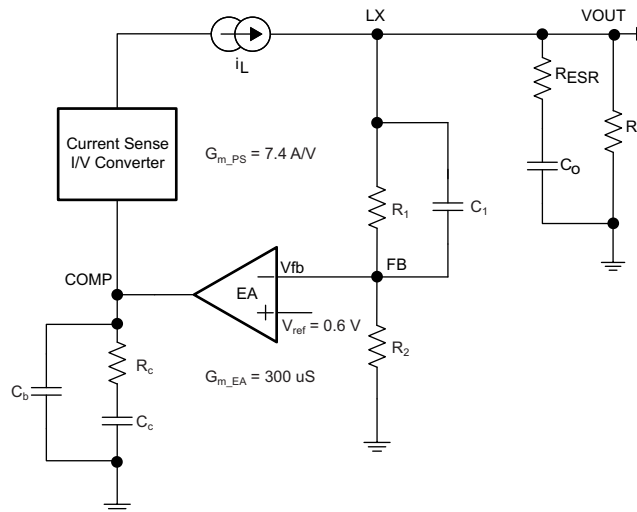


Figure 41. DC/DC Loop Compensation

10.2.3 Application Curves

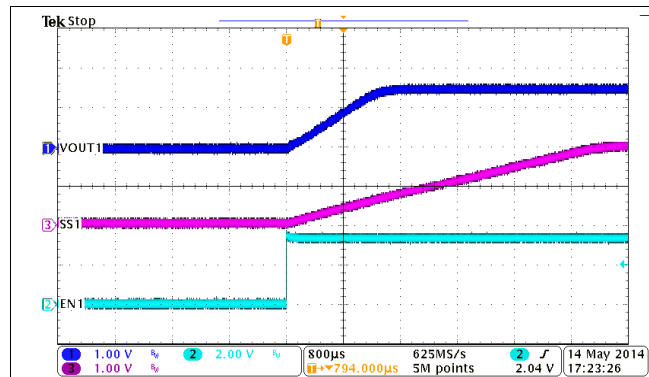


Figure 42. BUCK1, Soft-Start, Iout = 3 A

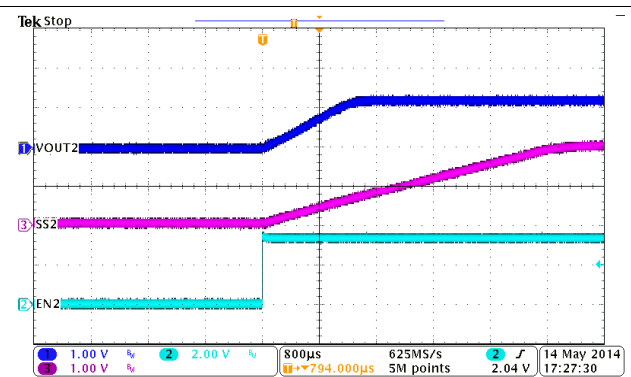


Figure 43. BUCK2, Soft-Start, Iout = 2 A

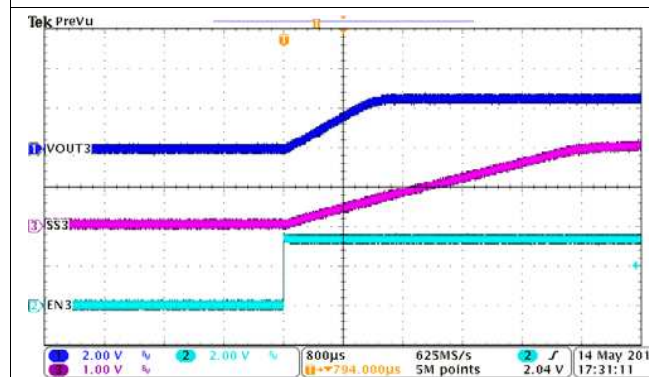


Figure 44. BUCK3, Soft-Start, Iout = 2 A

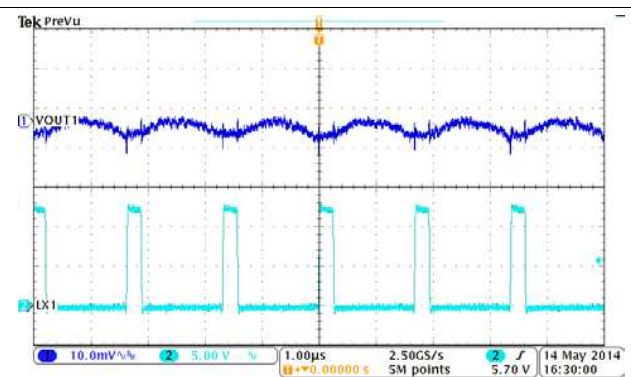


Figure 45. BUCK1, Output Voltage Ripple, Iout = 3 A

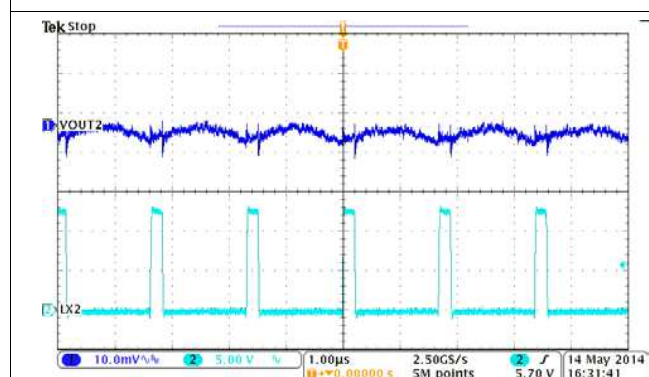


Figure 46. BUCK2, Output Voltage Ripple, Iout = 3 A

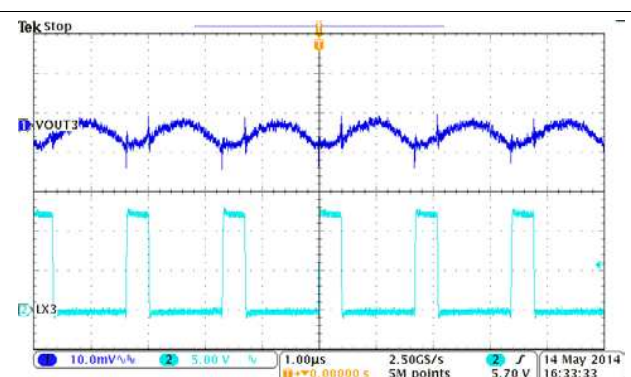


Figure 47. BUCK3, Output Voltage Ripple, Iout = 2 A

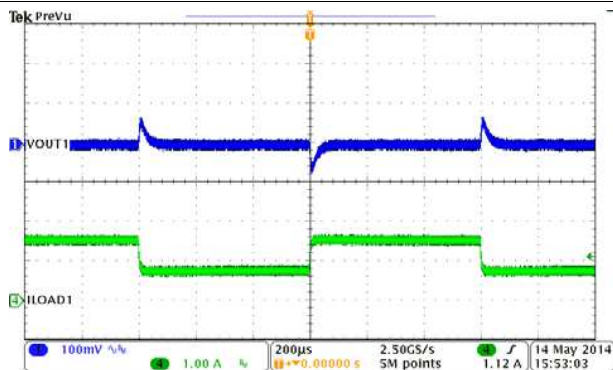


Figure 48. BUCK1, Load Transient, 0.75 to 1.5 A
SR = 0.25 A/µs

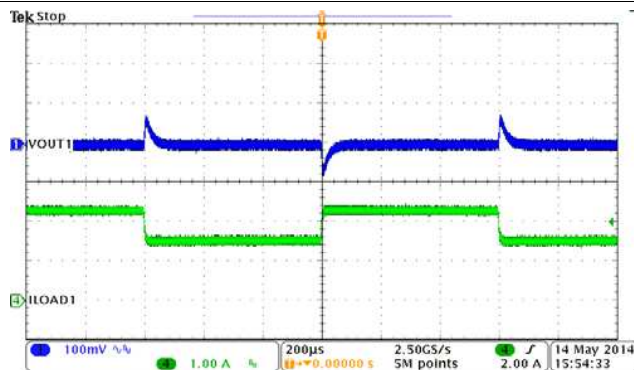


Figure 49. BUCK1, Load Transient, 1.5 to 2.25 A
SR = 0.25 A/µs

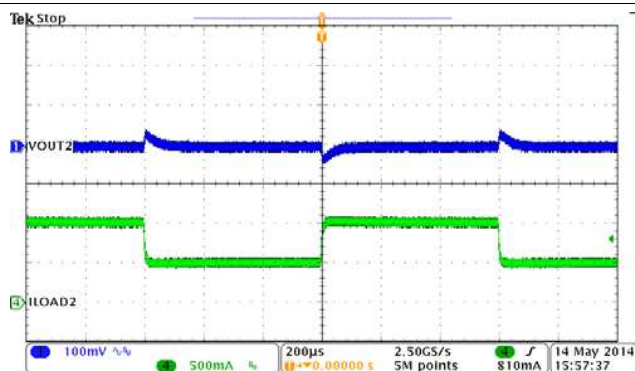


Figure 50. BUCK2, Load Transient, 0.5 to 1 A
SR = 0.25 A/µs

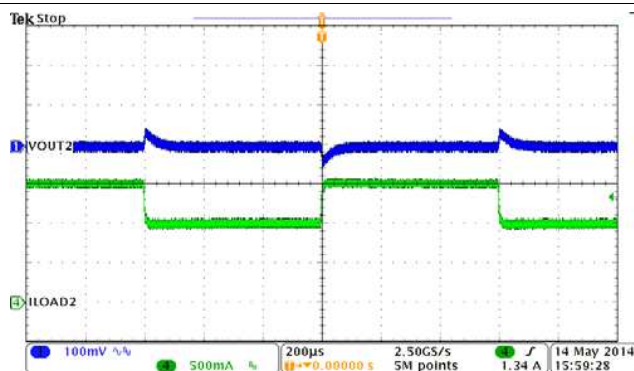


Figure 51. BUCK2, Load Transient, 1 to 1.5 A
SR = 0.25 A/µs

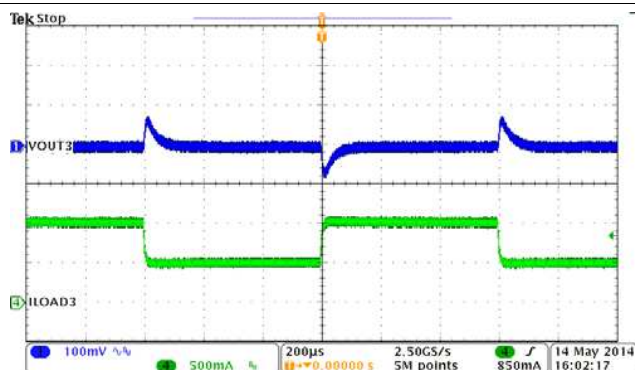


Figure 52. BUCK3, Load Transient, 0.5 to 1 A
SR = 0.25 A/µs

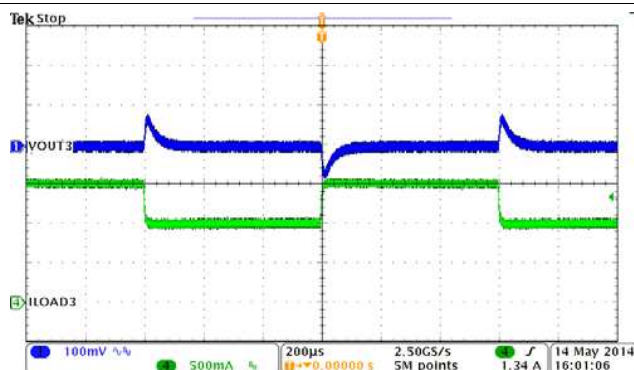


Figure 53. BUCK3, Load Transient, 1 to 1.5 A
SR = 0.25 A/µs

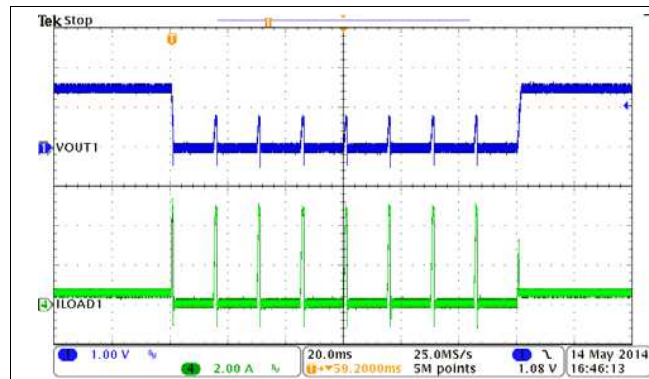


Figure 54. BUCK1, Hiccup and Recovery

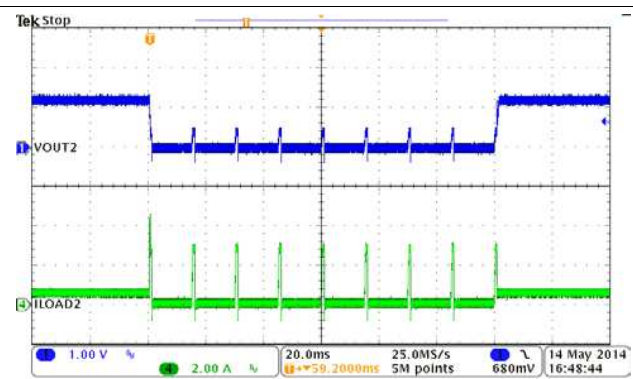


Figure 55. BUCK2, Hiccup and Recovery

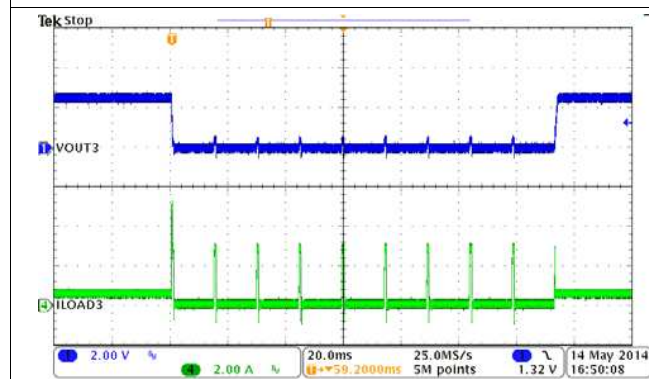


Figure 56. BUCK3, Hiccup and Recovery

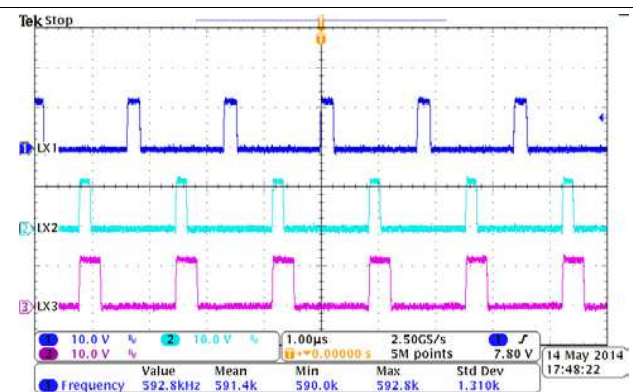


Figure 57. 180° Out-of-Phase

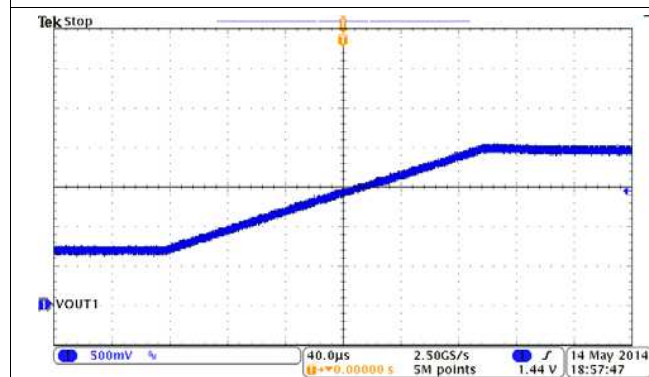


Figure 58. VID1 from 00 to 7F, SR = 10 mV/cycle

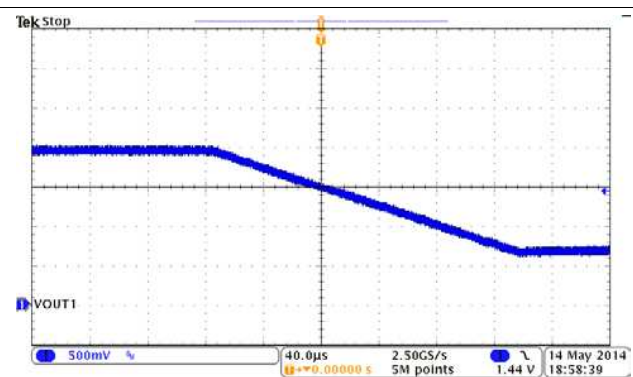


Figure 59. VID1 from 7F to 00, SR = 10 mV/cycle

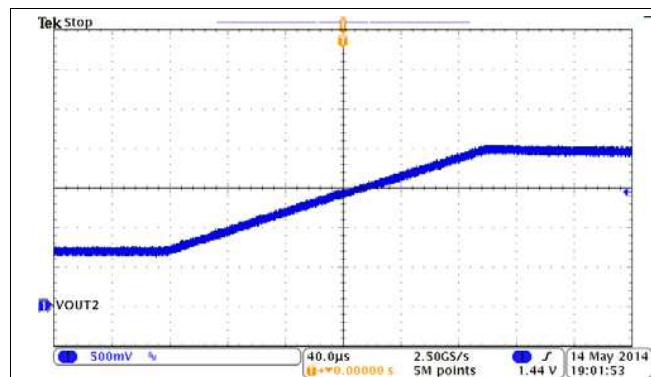


Figure 60. VID2 from 00 to 7F, SR = 10 mV/cycle

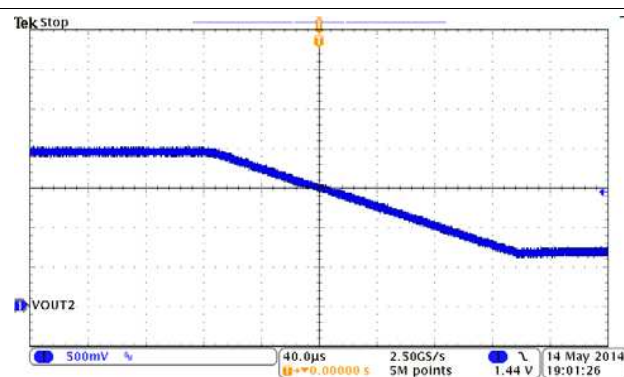


Figure 61. VID2 from 7F to 00, SR = 10 mV/cycle

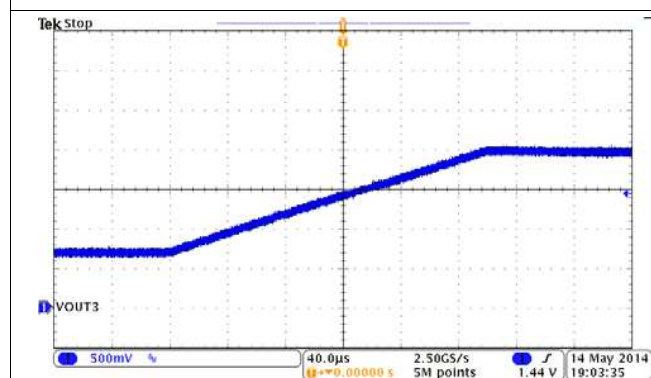


Figure 62. VID3 from 00 to 7F, SR = 10 mV/cycle

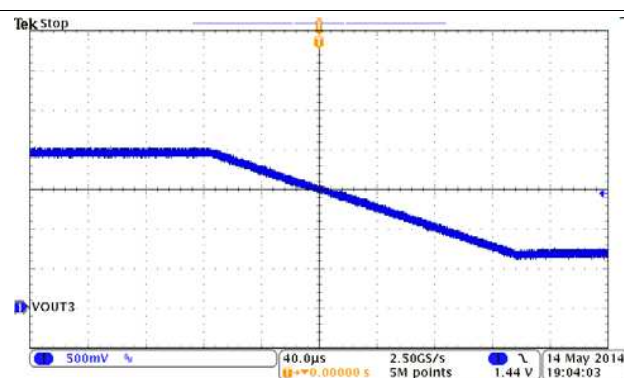
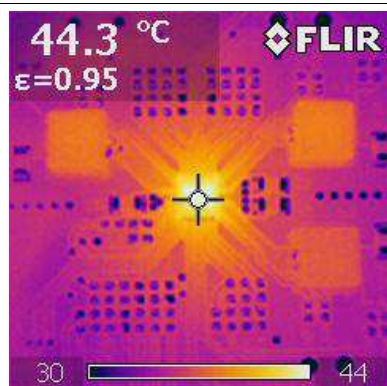
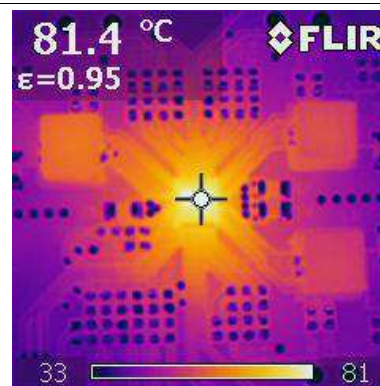


Figure 63. VID3 from 7F to 00, SR = 10 mV/cycle



VIN = 12 V; VOUT1 = 1.5 V / 1.5 A; VOUT2 = 1.2 V / 1 A
VOUT3 = 2.5 V / 1 A T_A = 26.8°C

Figure 64. Thermal Signature of TPS65263EVM, 4-Layer EVM Condition, 75 mm × 75 mm



VIN = 12 V; VOUT1 = 1.5 V / 3 A; VOUT2 = 1.2 V / 2 A
VOUT3 = 2.5 V / 2 A T_A = 26.8°C

Figure 65. Thermal Signature of TPS65263EVM, 4-Layer EVM Condition, 75 mm × 75 mm

11 Power Supply Recommendations

The devices are designed to operate from an input voltage supply range between 4.5 to 18 V. This input power supply should be well regulated. If the input supply is located more than a few inches from the TPS65263 converter additional bulk capacitance may be required in addition to the ceramic bypass capacitors. An electrolytic capacitor with a value of 47 μ F is a typical choice.

12 Layout

12.1 Layout Guidelines

The TPS65263 can be layout on 2-layer PCB, shown in [Figure 66](#).

Layout is a critical portion of good power supply design. See [Figure 66](#) for a PCB layout example. The top contains the main power traces for PVIN, VOUT, and LX. Also on the top layer are connections for the remaining pins of the TPS65263 and a large top side area filled with ground. The top layer ground area should be connected to the bottom layer ground using vias at the input bypass capacitor, the output filter capacitor and directly under the TPS65263 device to provide a thermal path from the exposed thermal pad land to ground. The bottom layer acts as ground plane connecting analog ground and power ground.

For operation at full rated load, the top side ground area together with the bottom side ground plane must provide adequate heat dissipating area. There are several signals paths that conduct fast changing currents or voltages that can interact with stray inductance or parasitic capacitance to generate noise or degrade the power supplies performance. To help eliminate these problems, the PVIN pin should be bypassed to ground with a low ESR ceramic bypass capacitor with X5R or X7R dielectric. Care should be taken to minimize the loop area formed by the bypass capacitor connections, the PVIN pins, and the ground connections. The VIN pin must also be bypassed to ground using a low ESR ceramic capacitor with X5R or X7R dielectric.

Since the LX connection is the switching node, the output inductor should be located close to the LX pins, and the area of the PCB conductor minimized to prevent excessive capacitive coupling. The output filter capacitor ground should use the same power ground trace as the PVIN input bypass capacitor. Try to minimize this conductor length while maintaining adequate width. The small signal components should be grounded to the analog ground path.

The FB and COMP pins are sensitive to noise so the resistors and capacitors should be located as close as possible to the IC and routed with minimal lengths of trace. The additional external components can be placed approximately as shown.

12.2 Layout Example

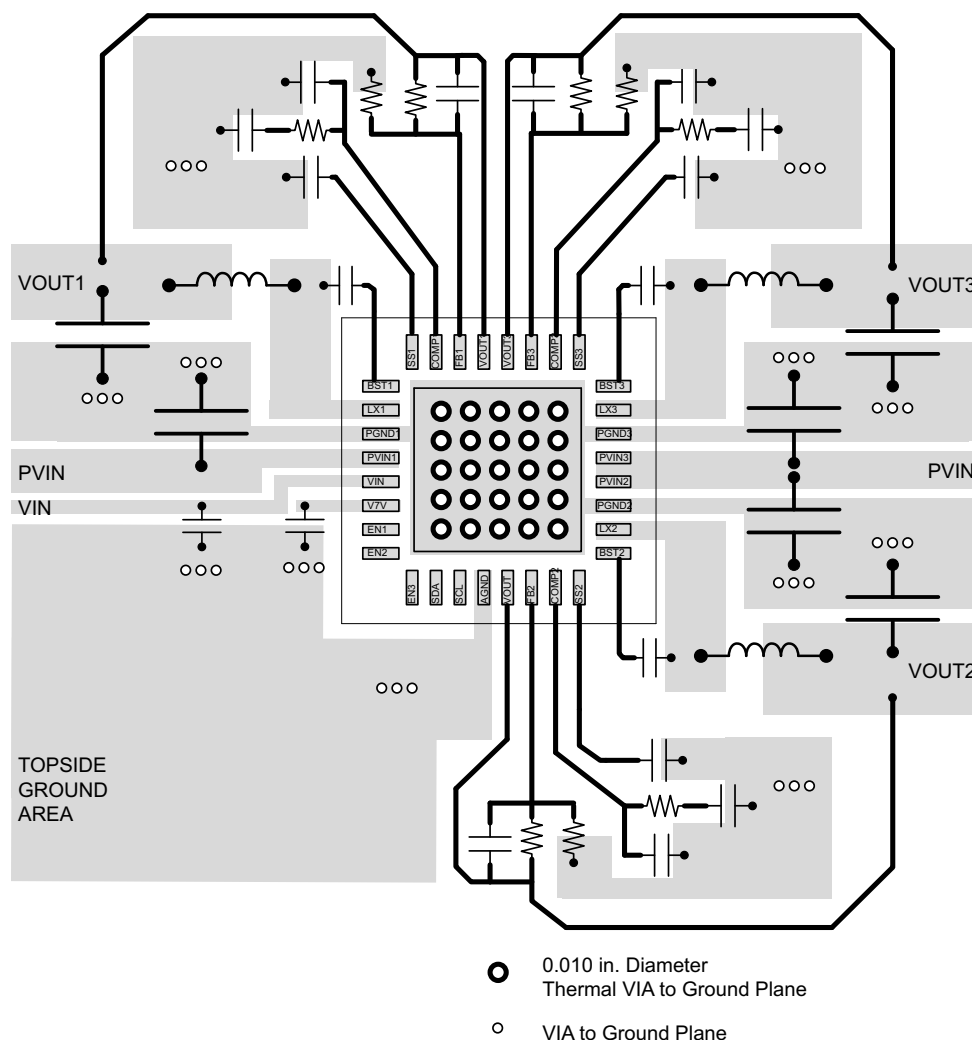


Figure 66. PCB Layout

13 Device and Documentation Support

13.1 Trademarks

NXP is a trademark of NXP Semiconductors.

13.2 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

13.3 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
TPS65263RHBR	ACTIVE	VQFN	RHB	32	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85	TPS 65263	Samples
TPS65263RHBT	ACTIVE	VQFN	RHB	32	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR		TPS 65263	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBsolete: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

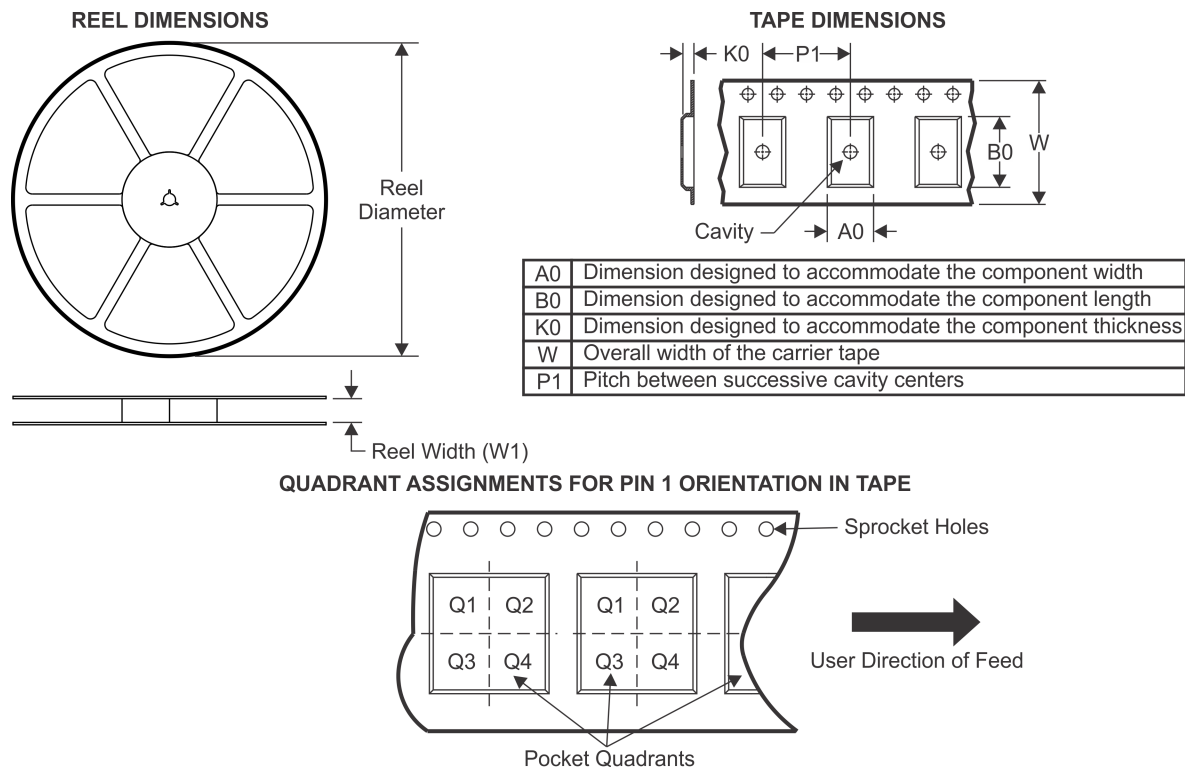
(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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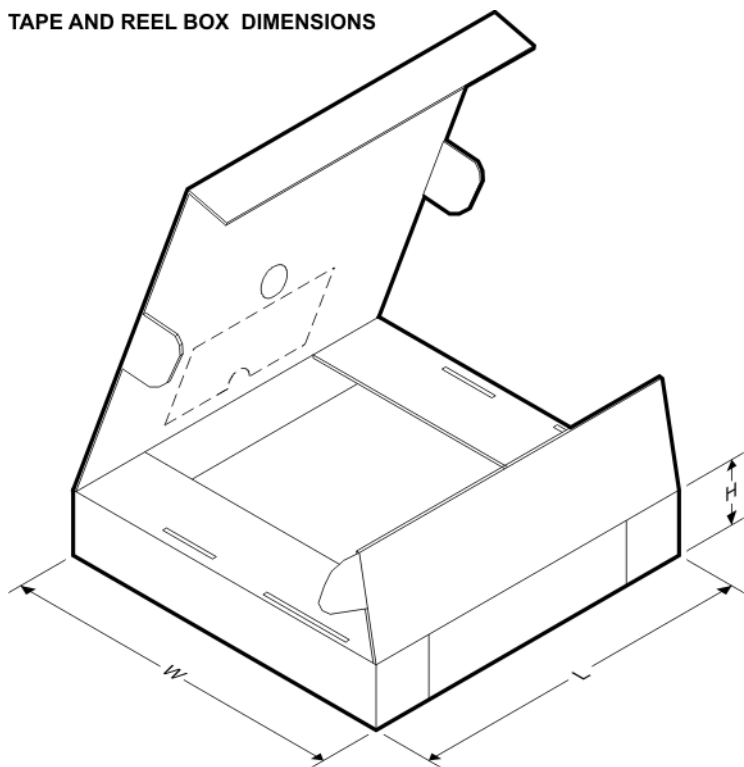
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TAPE AND REEL INFORMATION


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS65263RHBR	VQFN	RHB	32	3000	330.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
TPS65263RHBT	VQFN	RHB	32	250	180.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2

TAPE AND REEL BOX DIMENSIONS

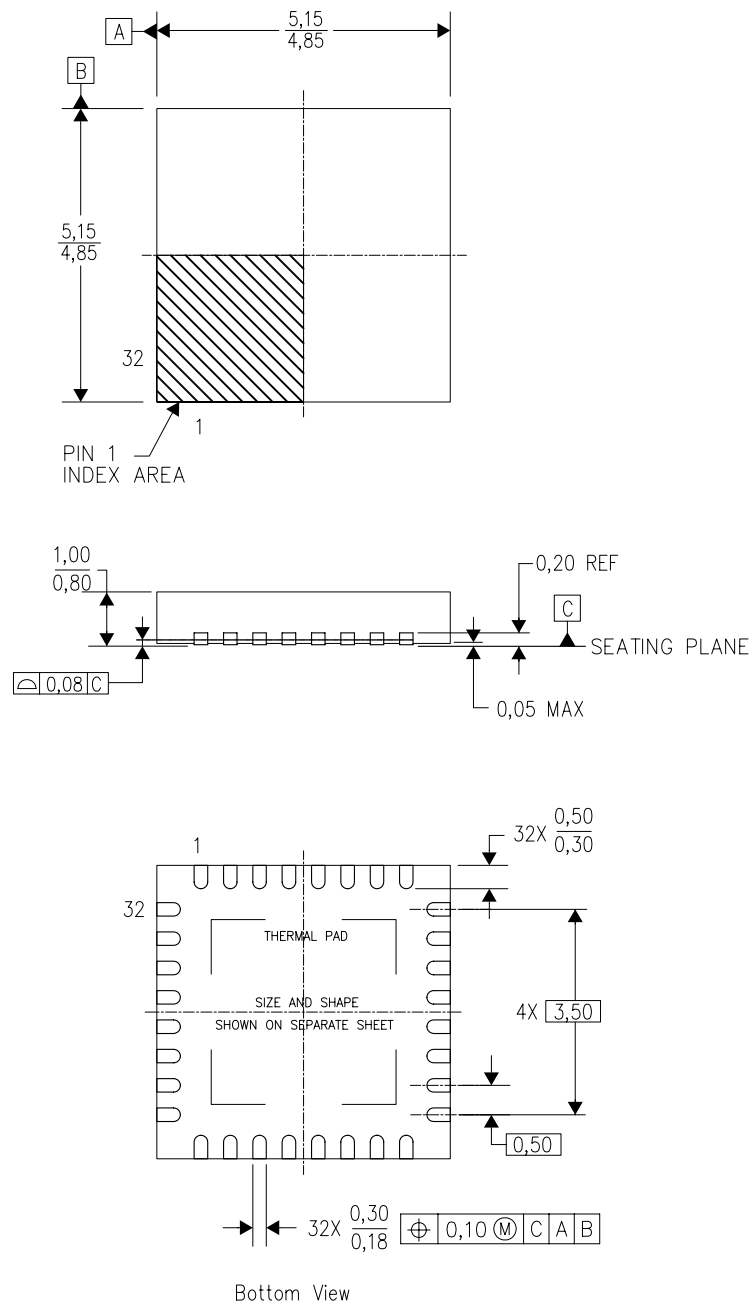


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS65263RHBR	VQFN	RHB	32	3000	367.0	367.0	35.0
TPS65263RHBT	VQFN	RHB	32	250	210.0	185.0	35.0

RHB (S-PVQFN-N32)

PLASTIC QUAD FLATPACK NO-LEAD



4204326/D 06/11

- NOTES:
- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
 - B. This drawing is subject to change without notice.
 - C. QFN (Quad Flatpack No-Lead) Package configuration.
 - D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
 - E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.
 - F. Falls within JEDEC MO-220.

RHB (S-PVQFN-N32)

PLASTIC QUAD FLATPACK NO-LEAD

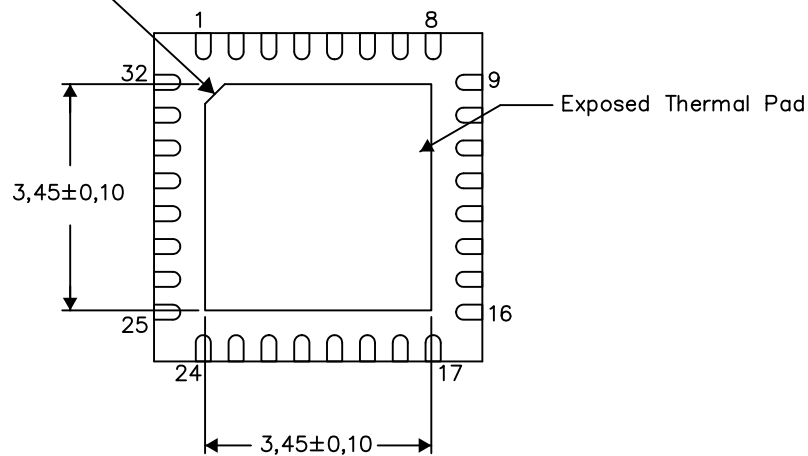
THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.

PIN 1 INDICATOR
(OPTIONAL)



Bottom View

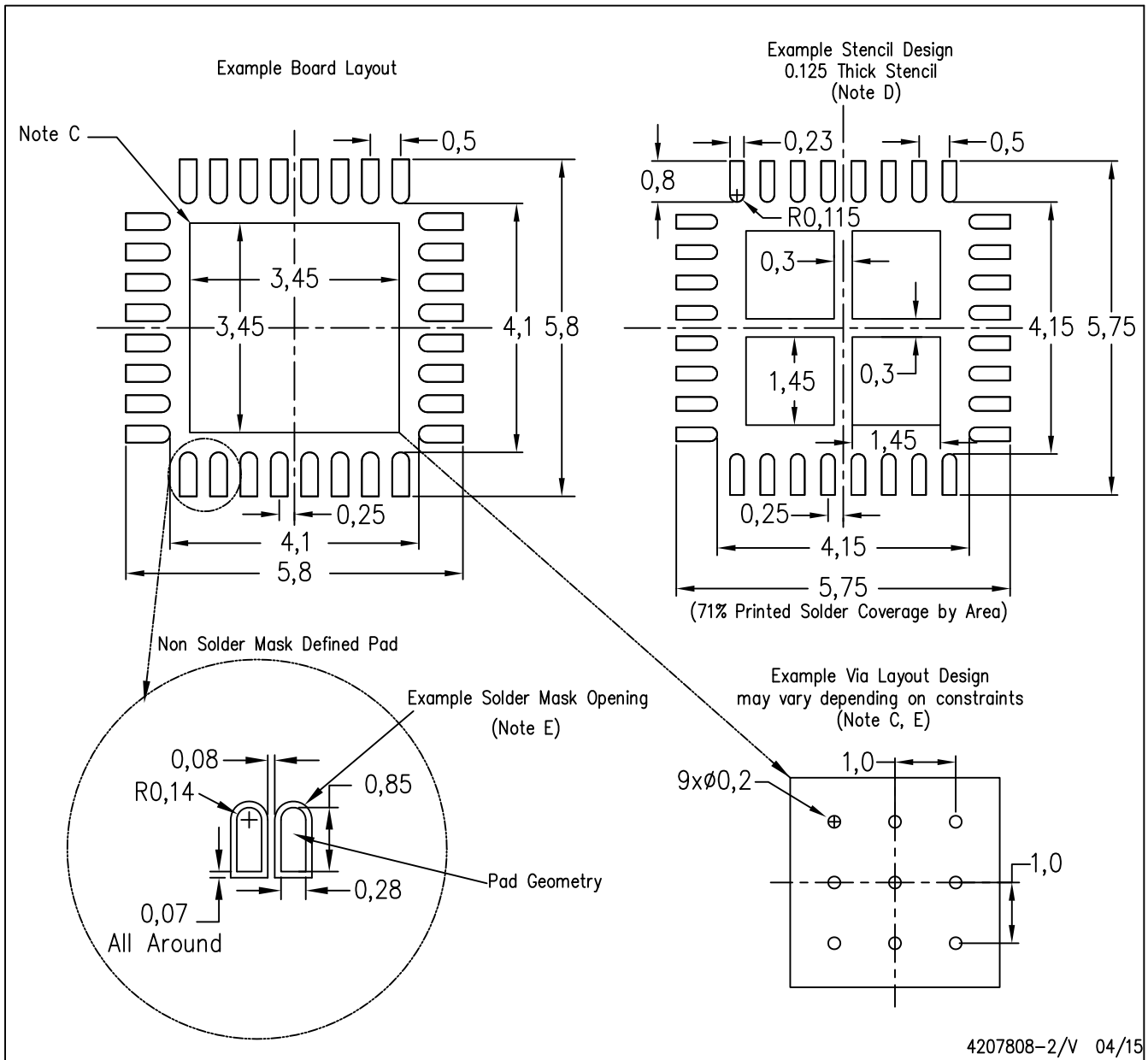
Exposed Thermal Pad Dimensions

4206356-2/AC 05/15

NOTE: A. All linear dimensions are in millimeters

RHB (S-PVQFN-N32)

PLASTIC QUAD FLATPACK NO-LEAD



- NOTES:
- All linear dimensions are in millimeters.
 - This drawing is subject to change without notice.
 - This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <<http://www.ti.com>>.
 - Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
 - Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for any larger diameter vias placed in the thermal pad.

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