



TFmini Micro LiDAR Module (I2C)

1. Product Description

Based on TOF (Time of Flight) principle and integrated with unique optical and electrical designs, the product uses 850nm IR light source to achieve stable, precise, high sensitivity and high-speed distance detection.

The built-in algorithm adapted to different application environments can guarantee an excellent ranging performance at a low cost and in a tiny volume. Various adjustable configurations are available for flexible use by customers, which is more suitable for customers' product needs.

2. Technical Specifications and Parameters

Table 1 Main characteristic parameters of TFmini-I²C

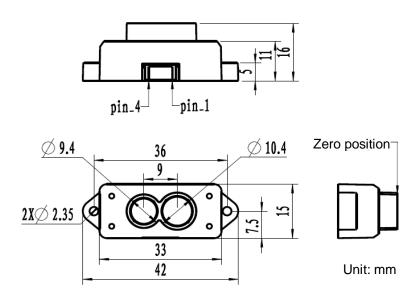
Parameter name		Parameters	
	Detecting range	0.3m~12m [®]	
Product	Accuracy of measurement	±4cm@ (0.3-6m) ² ±6cm@ (6m-12m)	
performance	Range resolution	1cm	
	Light intensity	70klux	
	Operating temperature	0~60℃	
	Light source	LED	
Optical parameters	Center wavelength Receiving half-angle	850nm 1.15°	
	Emitting half-angle	1.5°	
	Power supply voltage	5V	
	Average current	≤120mA	
Electrical parameters	Average power consumption	≤0.6W	
parameter c	Peak current	800mA	
	Electrical level	3.3V	
	Wire length	10cm	
Miscellaneous	Casing material	ABS+PC	
wiscenaneous	Weight	4.7g	
	Storage temperature	-20℃~75℃	

① Detect range based on a standard whiteboard with reflectivity 90% in indoor conditions

 $^{\@}Delta$ Due to switching of range scale, the measuring value of individual point may differ from the actual value over a detecting range of 0.3m to 2m, however, the deviation is within ± 6 cm.







3. Appearance and Construction

Fig. 1 Dimensions of TFmini-I²C module

4. Definition of Product Connectors

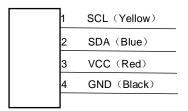


Fig. 2 Sequence of TFmini-I2C lines

TFmini adopts GH1.25-4p connector. The line sequence is shown in Fig.2. Refer to Fig.1 for the position of corresponding pins.

5. Communication Protocol and Data Format

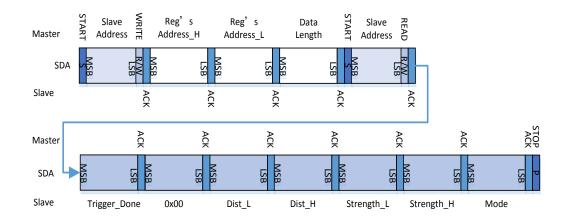
Table 2 Communication Protocol

Communication port	I ² C
Maximum transmission rate	400kHz
Master-slave mode	Slave mode
Address range	0X07~0X78
Default address	0x07

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Table 3 Time sequence of radar data reading by I²C host

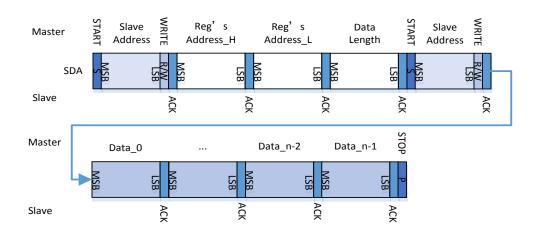


Description of Data Encoding				
START	Start signal			
STOP	Stop signal			
Slave Address	The slave address is 0x07 by default, and it is configurable.			
R/\overline{W}	Read/write flag; R/\overline{W} =1 indicates READ, and R/\overline{W} =0 indicates WRITE.			
ACK	ACK Master-slave response			
Reg's Address_H	Higher 8 bits of the register address. When reading distance information, Reg's Address_H=0x01			
Reg's Address_L	Lower 8 bits of the register address. When reading distance information, Reg's Address_L=0x02			
Data Length Number of bytes read/written. When reading distance information , Data Length=0x07				
Trigger_Done	Distance measurement completion flag When ranging information is valid, Trigger_Done = 0x01 When ranging information is invalid, Trigger_Done = 0x00, and the user should ignore frame data.			
Dist_L	Lower 8 bits of the distance value.			
Dist H	Higher 8 bits of the distance value.			
Strength L Lower 8 bits of the signal strength value.				
Strength H	Higher 8 bits of the signal strength value.			
Range scale Value range: 00 (short distance), 03 (intermediate distance) and 07 (long distance) Automatic switching by default				

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Table 4 Time sequence of I²C configuration radar register



Description of Data Encoding				
START	Start signal			
STOP	Stop signal			
Slave Address	The slave address is 0x07 by default, and it is configurable.			
R/\overline{W}	Read/write flag: $\mathbb{R}/\overline{\mathbb{W}=1}$ indicates READ; $\mathbb{R}/\overline{\mathbb{W}=0}$ Indicates WRITE.			
ACK	Master-slave response			
Reg's Address_H	Higher 8 bits of the register address			
Reg's Address_L	Low 8 bits of the register address			
Data Length	Number of bytes read/written. Data_0 ~ Data_n-1 (total bytes)			
Data is	Register configuration value. For a double-byte parameter, the lower 8 bits are located in front of the higher 8 bits. Mapping of data to register address:			
Data_n	Reg's Address+0	Reg's Address+1		Reg's Address+n-1
	Data_0	Data_1		Data_n-1

6. Relevant Configuration Registers

Table 5 Description of Configuration Radar Registers of I²C

(Register name)	(Reg's Address)	Value range	Description	Default
(Register Hame)	(iteg 3 Address)	value range	Description	value







Slave address	0x0026	[0x78, 0x07]	It takes effect only after being turned on again	0x07
Fixed range scale	0x0050	0x00, 0x03, 0x07	1	0x00
Ranging mode	0x0051	[0xFF, 0x00]	0x00 indicates automatic switching among ranging modes. Non-zero indicates fixed range scale.	0x00
Measuring range output	0x0055	[0xFF, 0x00]	0x00 indicates that the measuring range output limiting mode is disabled; Non-zero indicates that the measuring range output limiting mode is enabled.	0x01
Measuring range output limiting threshold	[0x0057, 0x0056]	[0xFFFF, 0x0000]	Unit: mm	12000
Signal strength threshold value (lower limit)	[0x0059, 0x0058]	[0xFFFF, 0x0000]	1	20
Signal strength threshold value (upper limit)	[0x005B, 0x005A]	[0xFFFF, 0x0000]	/	65535
Upper limit of signal strength threshold value	[0x005D, 0x005C]	[0xFFFF, 0x0000]	Unit: mm	0
Unit of distance data	0x0066	[0xFF, 0x00]	0x00 indicates that distance is in millimeters (mm); Non-zero indicates distance is in centimeters (cm).	0x01
Restore default configuration	0x0070	0x02	0x02 indicates that the Client mode is restored	/

Note: For double-byte parameters, the higher 8 bits of parameter data is stored in the higher 8-bit address while the lower 8 bits of parameter data is stored in the lower 8-bit address.

7. Product Certification Standards





EN62471:

Photobiological Safety Certifications



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